

# Digital Communications 1

## Written exam on June 25, 2019

Institute of Telecommunications

TU Wien

**Please note:**

- You may use the official lecture notes, a pocket calculator, and a collection of mathematical formulas.
- Personal notes, materials from exercise classes, and pre-calculated problems may not be used.
- Legible writing and a clear layout of your derivations and solutions are absolutely necessary!
- Provide detailed derivations. When using results from the lecture notes, they must be explicitly referenced.

**Problem 1 (20 credits)**

Consider passband PAM transmission using the QPSK signal constellation  $\mathcal{A} = \{1, j, -1, -j\}$ . The transmission is ISI-free with complex gain factor  $p[0] = 1 - j$ . The receiver performs symbolwise ML detection. The real part and the imaginary part of the noise at the slicer input,  $z[k] = z_R[k] + jz_I[k]$ , are statistically independent zero-mean Gaussian random variables with variances  $\sigma_R^2 = 0.5$  and  $\sigma_I^2 = 1$ , respectively.

- a) Sketch the signal constellation.
- b) Sketch the signal constellation as seen at the slicer input and the decision regions of the symbolwise ML detector.
- c) Assume that the symbol  $j$  was transmitted. Calculate the probabilities of detecting 1,  $-1$ , and  $-j$ . Calculate the conditional symbol error probability for the case that  $j$  was transmitted.
- d) Calculate the conditional symbol error probabilities for the cases that 1,  $-1$ , and  $-j$  were transmitted. Calculate the unconditional symbol error probability.
- e) Assume that the transmitter decides to use only the symbols 1 and  $j$  but the receiver is not changed. How does this influence the unconditional symbol error probability?

**Problem 2 (20 credits)**

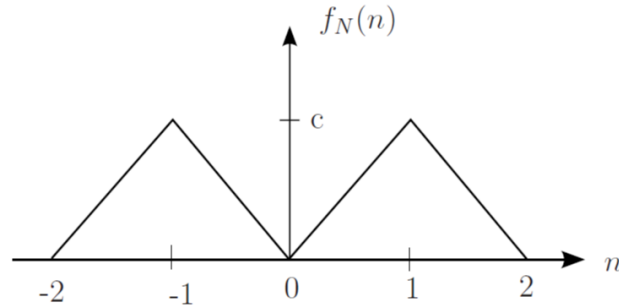
Consider a passband PAM system with received pulse

$$h(t) = e^{-t/T_s}u(t) + e^{-(t/T_s - a)}u(t - aT_s), \quad \text{where } a > 0.$$

- a) Specify the receive filter  $f(t)$  that minimizes the noise enhancement of the ZF equalizer. Use this receive filter in the following.
- b) Find a function  $\phi(t)$  such that  $h(t) = \phi(t) + \phi(t - aT_s)$ . Calculate  $r_\phi(\tau) = \int_{-\infty}^{\infty} \phi(t)\phi^*(t - \tau)dt$ .
- c) Calculate the equivalent discrete-time pulse  $p[k]$  at the slicer input.  
*Hint: Use your result from b).*
- d) Find the value of  $a$  such that  $p[0] = 2T_s$ .
- e) Assume that the transmit symbols  $A[k]$  are white and equally likely with symbol alphabet  $\mathcal{A} = \{1, -1\}$ . Determine the value of  $a$  that maximizes the SNR at the slicer input.

### Problem 3 (20 credits)

Consider transmission of a single symbol  $A \in \{-1, 0\}$  over a channel with additive noise  $N$ , which is distributed as shown below.



The transmission probabilities are defined as  $P\{A = 0\} = p$ .

- a) Calculate the constant  $c$  and the MAP decision rule.
- b) Calculate the ML decision rule and the corresponding symbol error probability.
- c) In the following assume that the receiver knows the sign of the noise  $N$  and uses this additional information for detection.
  - c1) Assume  $N > 0$ . Sketch the conditional noise pdf for  $N > 0$ .
  - c2) Calculate the ML decision rule for  $N > 0$  and for  $N < 0$ .
  - c3) How large is the symbol error probability of the ML detector that knows the sign of  $N$ ?

**Problem 4 (20 credits)**

Consider a passband PAM system with an ML sequence detector. In the equivalent discrete-time baseband domain, the channel is described by the folded spectrum

$$S_h(z) = \frac{8z^2 + 65z + 8}{8z}.$$

Furthermore, the channel adds white Gaussian noise.

- a) Sketch the function  $S_h(e^{j\theta})$  for  $\theta \in [-\pi, \pi]$ .
- b) Find the poles and zeros of  $S_h(z)$ .
- c) Find a minimum phase factorization of  $S_h(z)$ .
- d) Calculate the transfer function and impulse response of the equivalent discrete-time system including the noise whitening filter.
- e) Consider the transmission of symbols  $A[k] \in \{1, j, -1, -j\}$ . Assume that the Viterbi algorithm is to be implemented at the output of the noise whitening filter. Sketch the state transition diagram.