

Digital Communications 1

Written exam on January 26, 2015

Institute of Telecommunications

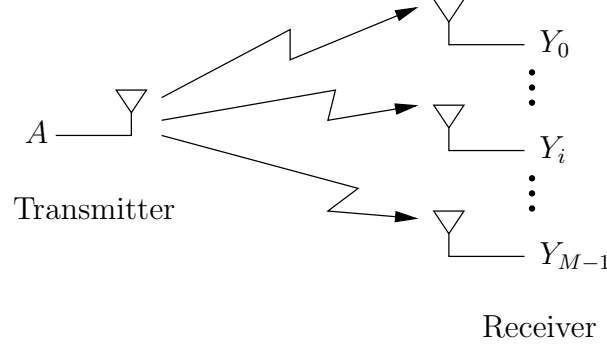
Vienna University of Technology

Please note:

- You may use the official lecture notes, a pocket calculator, and a collection of mathematical formulas.
- Personal notes, materials from exercise classes, and pre-calculated problems may not be used.
- Legible writing and a clear layout of your derivations and solutions are absolutely necessary!
- Provide detailed derivations. When using results from the lecture notes, they must be explicitly referenced.

Problem 1 (20 credits)

To mitigate fading effects in a mobile communication system, multiple receive antennas are considered (see figure):



The discrete-time channel associated with the i th receive antenna is given by $Y_i = H_i A + N_i$, $i = 0, 1, \dots, M - 1$. Here, $A \in \{0, 1\}$ is the transmit symbol ($P[A = 0] = 1/2$), Y_i is the receive symbol, H_i is a fading coefficient, and N_i is additive noise (all quantities are real-valued). The overall input-output relation can be summarized as

$$\mathbf{Y} = \mathbf{A}\mathbf{H} + \mathbf{N},$$

where $\mathbf{Y} = (Y_0 \dots Y_{M-1})^T$, $\mathbf{H} = (H_0 \dots H_{M-1})^T$, and $\mathbf{N} = (N_0 \dots N_{M-1})^T$. Both the channel coefficients and the noise are Gaussian with mean $\mathbb{E}\{\mathbf{H}\} = \mathbb{E}\{\mathbf{N}\} = \mathbf{0}$ and correlation matrices $\mathbb{E}\{\mathbf{H}\mathbf{H}^T\} = \rho^2 \mathbf{I}$ and $\mathbb{E}\{\mathbf{N}\mathbf{N}^T\} = \sigma^2 \mathbf{I}$ (\mathbf{I} is the $M \times M$ identity matrix). Transmit symbol A , channel coefficients H_i , and noise N_i are statistically independent.

- a) Determine the conditional probability density functions $f_{\mathbf{Y}|A}(\mathbf{y}|a = 0)$ and $f_{\mathbf{Y}|A}(\mathbf{y}|a = 1)$.
- b) Show that the ML receiver $\hat{A}_{\text{ML}} = \arg \max_{a \in \{0,1\}} f_{\mathbf{Y}|A}(\mathbf{y}|a)$ can be realized by comparing $z \triangleq \frac{1}{M} \|\mathbf{y}\|^2$ with a threshold γ (which does not depend on M). Determine γ .
- c) Calculate the conditional mean $\mu_a = \mathbb{E}\{Z|A = a\}$ and the conditional variance $\sigma_a^2 = \mathbb{E}\{(Z - \mu_a)^2|A = a\}$ of $Z = \frac{1}{M} \|\mathbf{Y}\|^2$ for $a = 0$ and $a = 1$. Use your results to show that the error probability of the ML receiver decreases with growing M .
Hint: For a zero-mean Gaussian random variable X , $\mathbb{E}\{X^4\} = 3(\mathbb{E}\{X^2\})^2$.

Problem 2 (20 credits)

Consider a bandpass PAM system with symbol period T_s , transmit pulse $g(t)$ (duration T_s , energy $E_g = 1$), and transmit symbols $A[k]$. The receive pulse in the equivalent baseband is $h(t) = g(t) + \alpha g(t - T_s)$ ($|\alpha| < 1$). The additive channel noise has a power spectral density of $N_0/2$. The receiver consists of a sampled matched filter, a noise whitening filter (based on a *causal* factorization), a slicer, and an equalizer.

- a) Determine the impulse response, transfer function, and noise power spectral density of the equivalent discrete-time model of the transmission system including the noise whitening filter (but not the equalizer).
- b) Calculate the zero-forcing equalizer (placed after the noise whitening filter). Compare the noise variance at the input and the output of the equalizer.
- c) Verify that the output of the noise whitening filter is free of precursor intersymbol interference.
- d) Determine the decision-feedback equalizer that completely removes postcursor intersymbol interference. *Note:* The noise whitening filter is used as the feedforward filter of the decision-feedback equalizer.

Problem 3 (20 credits)

Consider transmission of a symbol $A \in \{1, 4\}$. At the slicer input, the receiver observes a random variable Q that is corrupted by real-valued multiplicative noise Z , i.e.,

$$Q = A Z .$$

The noise is Laplace distributed, i.e.,

$$f_Z(z) = e^{-2|z-1|} .$$

- a) Calculate and sketch $f_{Q|A}(q|a)$ for $a = 1$ and $a = 4$.
- b) Calculate the probabilities $P\{Q > \eta_1 \mid A = 1\}$ and $P\{Q < \eta_2 \mid A = 4\}$ for $\eta_1 > 1$ and $\eta_2 < 4$.
- c) Consider ML detection. Determine the decision rule and sketch the decision intervals. Calculate the conditional symbol error probability $P\{\mathcal{E} \mid A = a\}$ for $a = 1$ and $a = 4$.
- d) Consider a detector using the following decision rule:

$$\hat{A} = \begin{cases} 1, & |Q - 1| < 0.5 \\ 4, & |Q - 4| < 0.5 \\ \text{undecided,} & \text{otherwise.} \end{cases}$$

Sketch the decision intervals. Calculate the conditional symbol error probabilities $P\{\hat{A} = 1 \mid A = 4\}$ and $P\{\hat{A} = 4 \mid A = 1\}$.

Problem 4 (20 credits)

Consider a passband PAM system with an ML sequence detector. In the equivalent discrete-time baseband domain, the channel is described by the folded spectrum

$$S_h(z) = \frac{8z^2 + 65z + 8}{8z}.$$

Furthermore, the channel adds white Gaussian noise.

- a) Sketch the function $S_h(e^{j\theta})$ for $\theta \in [-\pi, \pi]$.
- b) Find the poles and zeros of $S_h(z)$.
- c) Find a minimum phase factorization of $S_h(z)$.
- d) Calculate the transfer function and impulse response of the equivalent discrete-time system including the noise whitening filter.
- e) Consider the transmission of symbols $A[k] \in \{1, j, -1, -j\}$. Sketch the state transition diagram associated with the equivalent discrete-time system including the noise whitening filter.