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function [coordinates,newElements,varargout] ...
          = refineNVB(coordinates,elements,varargin)

%refineNVB: local refinement of finite element mesh by newest vertex
%           bisection, where marked elements are refined by bisec(3)
%
%Usage:
%
%[coordinates,elements,dirichlet,neumann] ...
%    = refineNVB1(coordinates,elements,dirichlet,neumann,marked)
%
%Comments:
%
%    refineNVB expects as input a finite element mesh described by the
%    fields coordinates,elements,dirichlet and neumann. The vector
%    marked contains the indices of elements which are refined by bisec(3).
%    Further elements will be refined by newest vertex bisection to obtain
%    a regular triangulation.  Note that elements(j,3) provides the index
%    of the newest vertex of the j-th element.
%
%    The function returns the refined mesh in terms of the same data as
%    for the input.
%
%Remark:
%
%    This program is a supplement to the paper
%    >> Efficient Implementation of Adaptive P1-FEM in Matlab <<
%    by S. Funken, D. Praetorius, and P. Wissgott. The reader should
%    consult that paper for more information.
%
%Authors:
%
%    S. Funken, D. Praetorius, P. Wissgott  10-07-08

markedElements = varargin{end};
nE = size(elements,1);
%*** Obtain geometric information on edges
[edge2nodes,element2edges,boundary2edges{1:nargin-3}] ...
    = provideGeometricData(elements,varargin{1:end-1});
%*** Mark edges for refinement
edge2newNode = zeros(max(max(element2edges)),1);
edge2newNode(element2edges(markedElements,:)) = 1;
swap = 1;
while ~isempty(swap)
    markedEdge = edge2newNode(element2edges);
    swap = find( ~markedEdge(:,1) & (markedEdge(:,2) | markedEdge(:,3)) );
    edge2newNode(element2edges(swap,1)) = 1;
end
%*** Generate new nodes
edge2newNode(edge2newNode~=0) = size(coordinates,1) + (1:nnz(edge2newNode));
idx = find(edge2newNode);
coordinates(edge2newNode(idx),:) ...
    = (coordinates(edge2nodes(idx,1),:)+coordinates(edge2nodes(idx,2),:))/2;
%*** Refine boundary conditions
for j = 1:nargout-2
    boundary = varargin{j};
    if ~isempty(boundary)
        newNodes = edge2newNode(boundary2edges{j});
        markedEdges = find(newNodes);
        if ~isempty(markedEdges)
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            boundary = [boundary(~newNodes,:); ...
                        boundary(markedEdges,1),newNodes(markedEdges); ...
                        newNodes(markedEdges),boundary(markedEdges,2)];
        end
    end
    varargout{j} = boundary;
end
%*** Provide new nodes for refinement of elements
newNodes = edge2newNode(element2edges);
%*** Determine type of refinement for each element
markedEdges = (newNodes~=0);
none = ~markedEdges(:,1);
bisec1   = ( markedEdges(:,1) & ~markedEdges(:,2) & ~markedEdges(:,3) );
bisec12  = ( markedEdges(:,1) &  markedEdges(:,2) & ~markedEdges(:,3) );
bisec13  = ( markedEdges(:,1) & ~markedEdges(:,2) &  markedEdges(:,3) );
bisec123 = ( markedEdges(:,1) &  markedEdges(:,2) &  markedEdges(:,3) );
%*** Generate element numbering for refined mesh
idx = ones(nE,1);
idx(bisec1)   = 2; %*** bisec(1): newest vertex bisection of 1st edge
idx(bisec12)  = 3; %*** bisec(2): newest vertex bisection of 1st and 2nd edge
idx(bisec13)  = 3; %*** bisec(2): newest vertex bisection of 1st and 3rd edge
idx(bisec123) = 4; %*** bisec(3): newest vertex bisection of all edges
idx = [1;1+cumsum(idx)];
%*** Generate new elements
newElements = zeros(idx(end)-1,3);
newElements(idx(none),:) = elements(none,:);
newElements([idx(bisec1),1+idx(bisec1)],:) ...
    = [elements(bisec1,3),elements(bisec1,1),newNodes(bisec1,1); ...
       elements(bisec1,2),elements(bisec1,3),newNodes(bisec1,1)];
newElements([idx(bisec12),1+idx(bisec12),2+idx(bisec12)],:) ...
    = [elements(bisec12,3),elements(bisec12,1),newNodes(bisec12,1); ...
       newNodes(bisec12,1),elements(bisec12,2),newNodes(bisec12,2); ...
       elements(bisec12,3),newNodes(bisec12,1),newNodes(bisec12,2)];
newElements([idx(bisec13),1+idx(bisec13),2+idx(bisec13)],:) ...
    = [newNodes(bisec13,1),elements(bisec13,3),newNodes(bisec13,3); ...
       elements(bisec13,1),newNodes(bisec13,1),newNodes(bisec13,3); ...
       elements(bisec13,2),elements(bisec13,3),newNodes(bisec13,1)];
newElements([idx(bisec123),1+idx(bisec123),2+idx(bisec123),3+idx(bisec123)],:) ...
    = [newNodes(bisec123,1),elements(bisec123,3),newNodes(bisec123,3); ...
       elements(bisec123,1),newNodes(bisec123,1),newNodes(bisec123,3); ...
       newNodes(bisec123,1),elements(bisec123,2),newNodes(bisec123,2); ...
       elements(bisec123,3),newNodes(bisec123,1),newNodes(bisec123,2)];


function [edge2nodes,element2edges,varargout] ...
= provideGeometricData(elements,varargin)

%provideGeometricData: returns geometric data for finite element mesh
%
%Usage:
%
%[edges2nodes,element2edges,dirichlet2edges,neumann2edges] ...
%    = provideGeometricData(elements,dirichlet,neumann)
%
%Comments:
%
%    provideGeometricData expects as input a finite element mesh described
%    by the fields elements, dirichlet, and neumann. The
%    function chooses a numbering of the edges and then return this numbering
%    related to nodes, edges, and the boundary conditions.
%
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%    edges2nodes(k) returns the indices of the two nodes of the k-th edge.
%    element2edges(j,k) provides the edge number of the edge between the two
%    nodes elements(j,k) and elements(j,k+1). dirichlet2edges(k) provides
%    the number of the k-th Dirichlet edge given by dirichlet(k,:). The same
%    applies for neumann2edges
%
%Remark:
%
%    This program is a supplement to the paper
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%    consult that paper for more information.
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nE = size(elements,1);
nB = nargin-1;
%*** Node vectors of all edges (interior edges appear twice)
I = elements(:);
J = reshape(elements(:,[2,3,1]),3*nE,1);
%*** Symmetrize I and J (so far boundary edges appear only once)
pointer = [1,3*nE,zeros(1,nB)];
for j = 1:nB
boundary = varargin{j};
if ~isempty(boundary)
I = [I;boundary(:,2)];
J = [J;boundary(:,1)];
end
pointer(j+2) = pointer(j+1) + size(boundary,1);
end
%*** Create numbering of edges
idxIJ = find(I < J);
edgeNumber = zeros(length(I),1);
edgeNumber(idxIJ) = 1:length(idxIJ);
idxJI = find(I > J);
number2edges = sparse(I(idxIJ),J(idxIJ),1:length(idxIJ));
[foo{1:2},numberingIJ] = find( number2edges );
[foo{1:2},idxJI2IJ] = find( sparse(J(idxJI),I(idxJI),idxJI) );
edgeNumber(idxJI2IJ) = numberingIJ;
%*** Provide element2edges and edge2nodes
element2edges = reshape(edgeNumber(1:3*nE),nE,3);
edge2nodes = [I(idxIJ),J(idxIJ)];
%*** Provide boundary2edges
for j = 1:nB
varargout{j} = edgeNumber(pointer(j+1)+1:pointer(j+2));
end
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