

Übungsaufgaben zur VU Computermathematik Serie 6

Exercise 6.1. Study the help pages

? interface

(concerning control of the user interface), and

? kernelopts

(concerning control of the behavior of the kernel), and get an overview. Try out what you find interesting and collect this material in a worksheet.

Exercise 6.2.

- a) Do you know how whether the following series are convergent and what the respective values are? Maple knows – test it:¹

$$\sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{2k-1} = \frac{\pi}{4}, \quad \sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{2k} = \frac{1}{2} \ln 2. \quad (1)$$

- b) Use `taylor` to compute the first terms of the Taylor expansion of the functions

$$f(x) = \arctan x, \quad f(x) = \ln(1+x)$$

with respect to $x_0 = 0$. From the result it is evident how the Taylor series of these functions look like. Note that the `arctan` - series converges to `arctan x` for all $x \in \mathbb{R}$, and the `ln(1+x)` - series converges to `ln(1+x)` for $-1 < x \leq 1$.

Now, turn the situation around: Specify these series in Maple using `sum`, summing up to `infinity`, and check whether Maple is able to identify them with the corresponding functions. Does Maple care about the convergence domain (which is finite for `ln(1+x)`)?

Furthermore, use these series to verify the formulas (1) by appropriate choice of x .

- c) Design a procedure `taycoe(f,x0,n)` which, for a given (infinitely differentiable) function $f(x)$, returns its n -th Taylor coefficient

$$\frac{f^{(n)}(x_0)}{n!}$$

for given $n \in \mathbb{N}$ and $x_0 \in \mathbb{R}$, and use it to design your own version of `taylor`, e.g., `mytaylor(f,n,x0)` generating the Taylor polynomial of degree n . Your procedure should return the polynomial function

$$h \mapsto \sum_{k=0}^n \frac{f^{(k)}(x_0)}{k!} h^k$$

in this way:

¹ `∞ = infinity`

```
return h->add(...);
```

Remark: This amounts to a naive, brute-force computation. E.g., to compute the 1001-th Taylor coefficient of $f(x) = \arctan x$, your procedure `taycoe` will compute the 1001-th derivative (a high-degree rational function) and evaluate it at $x_0 = 0$.

In contrast, the general form of the Taylor series of many standard functions like, e.g., $\arctan x$, is built-in to the Maple in an internal database as static knowledge. Furthermore, a number of more or less tricky symbolic algorithms for yielding general formulas for Taylor coefficients is internally implemented.

Exercise 6.3.

- a) Check by experiment the validity of the Leibniz formula for the n -th derivative of a product of two functions,

$$\frac{d^n}{dx^n} (f \cdot g)(x) = \sum_{k=0}^n \binom{n}{k} \frac{d^k}{dx^k} f(x) \cdot \frac{d^{n-k}}{dx^{n-k}} g(x),$$

for $n = 1, 2, 3, \dots$. Use the derivative operator `D`. (In Maple, the binomial coefficient is `binomial(n,k)`.)

- c) Design a procedure `htvol(n)` which computes the n -dimensional volume of a hypertetraeder $\subseteq \mathbb{R}^n$,

$$V_n = \int_{x_1=0}^1 \left(\int_{x_2=0}^{x_1} \left(\dots \int_{x_n=0}^{x_{n-1}} 1 \, dx_n \dots \right) dx_2 \right) dx_1$$

for given $n \in \mathbb{N}$. Testing $n = 1, 2, 3, \dots$ you see how the general solution V_n will look like (it can be easily verified by induction).

Exercise 6.4.

Consider the recursion

$$x_n := c x_{n-1} + a_n, \quad n = 1, 2, 3, \dots$$

with a parameter c and a given initial value x_0 .

- a) Implement this in form of a recursive procedure,

```
xrec := proc(n,x0,c,a) ... end proc;
```

Your procedure expects a function `a := n-> ...`. Check what happens when this function is not explicitly specified.

- b) Call your procedure with $n = 0, 1, 2, 3, \dots$ and use `expand` in order to find the general formula for the solution x_n . This is easy to see (and easy to prove by induction for general n).
- c) Consider numerical evaluation of the sequence x_n , e.g.,

```
seq(xrec(n,x0,c,a),n=0..N);
```

with numerically specified data `c` and `a(.)`, for larger values of N , e.g., $N = 1000$. Is this efficient? Compare this with a simple loop for computing the sequence. Compare computing times using the CPU clock `time()`.

Exercise 6.5.

a) Consider the two-step recursion

$$x_n := a x_{n-1} + b x_{n-2}, \quad n = 2, 3, 4, \dots \quad (2)$$

where starting values x_0 and x_1 are given in some way. We wish to find the general form of the solution. To this end we use the ansatz

$$x_n = \lambda^n$$

with some parameter λ and plug it into (2). Conclude that there are two possible values $\lambda = \lambda_1$ and $\lambda = \lambda_2$ such that the ansatz works. Use Maple to express λ_1 and λ_2 in terms of the arbitrary parameters a and b . (Depending on a and b , the solution may be real or complex).

Then, the general solution of recursion (2) is given by

$$c_1 \lambda_1^n + c_2 \lambda_2^n$$

with arbitrary constants c_1, c_2 .

b) Use a) in order to generate an explicit formula for the *Fibonacci numbers* F_n defined by $F_0 = 0$, $F_1 = 1$, and

$$F_n := F_{n-1} + F_{n-2}, \quad n = 2, 3, 4, \dots \quad (3)$$

Verify that your F_n indeed satisfy (3).

c) Use `plots[pointplot]` to plot the coordinate pairs $(x, y) = (0, F_0), (1, F_1), (2, F_2), (3, F_3), \dots$

Exercise 6.6. Proceed in an analogous way as in 6.5 to solve the recursion

$$x_n = x_{n-1} - x_{n-2} + x_{n-3}, \quad n = 3, 4, 5, \dots$$

with given initial values $x_0 = 0$, $x_1 = 1$, and $x_2 = 2$. (You may use variables with indices, `lambda[1]`, `lambda[2]`, `lambda[3]`, and `c[1]`, `c[2]`, `c[3]`.)

For two of the λ 's you will obtain complex values,² but the solution x_n is of course real. You should be able to verify by simplification and testing the recursion that the solution is given by

$$x_n = 1 - \cos \frac{n\pi}{2}, \quad n = 0, 1, 2, 3, \dots$$

In contrast to the Fibonacci sequence (see 6.5), this solution is bounded and oscillatory.

Exercise 6.7. Design a procedure `myrooti(x,n,tol,maxiter)` for numerical approximation of $y = \sqrt[n]{x}$ by means of a *interval bisection method*. Here we assume that $x \in (0, 1)$ and $n \in \mathbb{N}$ is given. We know that $\sqrt[n]{x} \in (0, 1)$, and the function $\sqrt[n]{x}$ is strictly monotonously increasing. The bisection method starts with $y = \frac{1}{2}$. If $y^n = x$, we are done. Otherwise, the solution is either contained in $[0, y]$ or in $[y, 1]$, respectively, depending on the sign of the residual $y^n - x$, and so on. Use this idea to program the bisection method, and realize it using a loop.

Implement this algorithm using exact (rational) arithmetic for given rational x . However, the solution will be irrational (algebraic) in general. Stop the iteration when the length of the current interval containing the true solution is $\leq \text{tol}$, where `tol` is a given tolerance, e.g., `tol = 1E-3` for moderate accuracy. The iteration should also be stopped when `maxiter` bisection steps have been performed without satisfying the tolerance.

² The imaginary unit is represented by the built-in variable `I`.

Note that `tol` and `maxiter` are actually not independent, because you can *predict* how many iterations will be sufficient to satisfy the given tolerance. The purpose of the parameter `maxiter` is simply to implement an ‘emergency exit’.

Procedure `myrooti` should return

```
[[yleft,yright],converged] or y
```

In the first case, `[yleft,yright]` represents an interval containing the true solution, and `converged=true` if it satisfies the tolerance, otherwise `converged=false` (this occurs if the iteration stops prematurely at `maxiter` iterations). The second case indicates that the *exact* solution `y` has been found (special case).

(Note that in practice, such an algorithm will be implemented in floating point arithmetic, e.g., by using `evalf`. Also note that bisection converges because $\sqrt[n]{x}$ is monotone, but it converges rather slowly.)

Exercise 6.8. The package `plots`, to be activated by

```
with[plots];
```

contains many different plotting functions:

```
animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d, conformal,
conformal3d, contourplot, contourplot3d, coordplot, coordplot3d, densityplot, display,
dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot, implicitplot3d,
inequal, interactive, interactiveparams, intersectplot,
listcontplot, listcontplot3d, listdensityplot,
listplot, listplot3d, loglogplot, logplot, matrixplot, multiple, odeplot, pareto,
plotcompare, pointplot, pointplot3d, polarplot, polygonplot, polygonplot3d, polyhedra_supported,
polyhedraplot, rootlocus, semilogplot, setcolors, setoptions, setoptions3d, spacecurve,
sparsematrixplot, surfdata, textplot, textplot3d, tubeplot
```

Look at the documentation of this package and collect some cases of interest to you in a worksheet. Also play with options in order to produce ‘nice-looking’ results.

In particular, this package contains the useful function `display` which allows you to display several plots simultaneously, e.g., like in

```
p0 := plot(0,x=0..1);
pf := plot(x^2,x=0..1);
display(p0,pf);
```
