Übungsaufgaben zur VU Computermathematik Serie 6

Einige plot-Befehle und einige weitere Befehle (z.B. coeff, degree, piecewise) wurden in der VO noch nicht genauer besprochen. Dafür werden jeweils Hinweise gegeben. Konsultieren Sie für genauere Details die Maple-Hilfe.

Exercise 6.1. Parametric plots.

a) The *Möbius strip* is a two-dimensional manifold in \mathbb{R}^3 which is not orientable. A parametric representation is given by the coordinate functions

 $\begin{aligned} x(\varphi,t) &= \cos \varphi \left(r + t \cos(\varphi/2) \right) \\ y(\varphi,t) &= \sin \varphi \left(r + t \cos(\varphi/2) \right) \qquad (\varphi \in [0,2\pi], \ t \in [-r,r]) \\ z(\varphi,t) &= t \sin(\varphi/2)) \end{aligned}$

Here, 2r is the width of the strip (for a given numerical value r > 0).

Use plot3d and play with plot parameters in order to produce a nice plot:

plot3d([x(phi),t),y(phi,t),z(phi,t)],phi=0..2*Pi,t=-r..r,...);

b) Given a curve in the plane in parametric form, e.g., the Archimedian spiral

 $\begin{aligned} x(\varphi) &= \varphi \, \cos \varphi \\ y(\varphi) &= \varphi \, \sin \varphi \end{aligned} \qquad (\varphi \ge 0)$

you may expect that this can be plotted in analogy to a) using plot in the form

plot([x(phi),y(phi)],phi=0..phimax,...);

(with a chosen value for phimax). Try out – what happens? Consult the help page for plot to check how to realize such a two-dimensional *parametric plot*. Play with plot parameters in order to produce a nice plot of the spiral and of some other curve of your choice.

Hint: Note that you also can manipulate a plot interactively in various ways using the right mouse button or using the context menu shown on top when you click into the plot window.

Exercise 6.2. Manipulating polynomials. Complex arithmetic and harmonic polynomials.

a) Design a function polcoe(p,z) which expects a polynomial expression

 $c_0 + c_1 z + c_2 z^2 + \dots c_n z^n$

in the variable \mathbf{z} as arguments and returns the list of coefficients $[c_0, c_1, \ldots, c_n]$.

Hint: Use degree and coeff.

- **b)** Design a function for the reverse operation.
- c) Choose an arbitrary polynomial p(z) with real or complex coefficients, e.g. $p(z) = (3+i)z^3 iz^2 + 5z 1 i$. Then, using

x,y:='x','y': assume(x,real): assume(y,real):

declare the variables x, y to represent *real* values. Now evaluate p(x+I*y) using evalc, and extract real and imaginary parts using Re and Im. This yields two bivariate polynomials u(x, y) and v(x, y) with real coefficients in the variables x and y. Now, evaluate (possibly using simplify)

$$\frac{d^2u}{dx^2} + \frac{d^2u}{dy^2} \qquad \text{and} \qquad \frac{d^2v}{dx^2} + \frac{d^2v}{dy^2}$$

What do you observe?

Exercise 6.3. Smoothness analysis for a real function.

Consider the function $f: \mathbb{R} \to \mathbb{R}$, defined by

$$f(x) = \sqrt{1 + x^2 + \sqrt{x^4 + \sqrt{x^6}}}$$

a) Use Maple to check whether f' and f'' are well-defined and continuous at x = 0, possibly in the sense of continuous extension (*hebbare Unstetigkeit*).

Hint: Use limit.

b) Generate a plot showing the graphs of f, f', and f'' over an interval containing 0. Play with plot-parameters in order to produce a nice-looking plot.

Exercise 6.4. Some elementary calculus.

a) Use Maple to perform a complete analysis (Kurvendiskussion) for the real function

 $f(x) = \arctan(x^3)$

including a plot. Also, use pointplot and display from the plots package to add markers for special points (zeros, local minima, local maxima, turning points) to the plot. Use different colors.

b) Same as **a**), for the real function

$$f(x) = \frac{\left(\ln x\right)^2}{x}$$

Exercise 6.5. An extremal value problem. (See figure:) A rod is positioned as shown in the figure. Its length L depends on the angle α ,

with $L(\alpha) \to \infty$ for $\alpha \downarrow 0$ and for $\alpha \uparrow \frac{\pi}{2}$.

For what angle $\alpha \in (0, \frac{\pi}{2})$ does the length $L = L(\alpha)$ become minimal? Determine the minimal length and the corresponding distance x (see figure).

Solve this problem with the help of Maple.

At the end, evaluate the results in floating point using evalf.

Also, give the resulting value for α in degrees $^{\circ}$.

Remark: The minimal length is *not* given by L = 15 m.

Exercise 6.6. Functions defined in a piecewise way.

Let a function f(x) defined in a piecewise manner, e.g.

$$f(x) := \begin{cases} -1, & x < 0\\ 0, & x = 0\\ 1+x, & x > 0 \end{cases}$$

a) Design a function which, using if ... end if or 'if'(...), implements this (or a similar) example. Can you differentiate or integrate this function using diff,D, or int? Can you plot it? If not, try plot('f(x)',...)

- b) Alternative: Define the same function using the piecewise construct (look at the help page), and try again. Evaluate its indefinite integral and a definite integral.
- c) Assume that X is a strictly monotonically ordered list of numbers representing points on the real line, and let Y represent a list of function values, with nops(Y) = nops(X)-1. Design a procedure generate_stepfunction(X,Y) which uses the piecewise construct to return the corresponding step function (*Treppenfunktion*)

$$f(x) := \begin{cases} 0, & x < x_1 \quad (\text{i.e., for } x \in (-\infty, x_1)) \\ y_1, & x < x_2 \quad (\text{i.e., for } x \in [x_1, x_2)) \\ y_2, & x < x_3 \quad (\text{i.e., for } x \in [x_2, x_3)) \\ \vdots & \vdots \\ y_{n-1}, & x < x_n \quad (\text{i.e., for } x \in [x_{n-1}, x_n)) \\ 0, & \text{otherwise} \quad (\text{i.e., for } x \ge x_n) \end{cases}$$
 $(n = \text{nops}(X))$

Choose an example and plot the resulting step function. *Hint:* Use seq to generate the piecewise construct.



Exercise 6.7. Error analysis of some numerical integration methods.

If a definite integral

$$J(f) := \int_{a}^{b} f(x) \, dx$$

cannot be exactly determined, numerical approximation methods are applied.¹ We consider simple examples of such methods which only require evaluation of some function values. For simplicity, we consider the case a = 0 and b = h; think of h as the length of a small interval. In the following, f is any function (not explicitly specified).

a) A simple integration scheme is the *trapezodial rule* (with an obvious geometric interpretation)

$$T(f) := \frac{h}{2} (f(0) + f(h)) \approx J(f) = \int_0^h f(x) \, dx$$

Use int and taylor to compute the Taylor expansion of the error T(f) - J(f) with respect to the variable h at 0. What is the leading power of h in this expansion? (This is called the *order* of the approximation.) In what way does the leading error term depend on the integrand f?

b) Now we construct a better approximation method. Use the ansatz

$$S(f) := h \left(a f(0) + b f(\frac{h}{2}) + a f(h) \right)$$

and again use taylor to compute the Taylor expansion of the error S(f) - J(f). Can you find coefficients a and b such that the leading power of h in this expansion is 5? In what way does the resulting leading error term depend on the integrand f?

c) Test both numerical methods on a simple example (e.g., $f = \exp, h = 0.1$) and compare the results. Use evalf.

Exercise 6.8. Two small procedures.

- a) Design a procedure checktype(A,t) which does the same job as the function checktype from 5.4 d).
 Hint: Use logical operations and evalb within a for loop.
- b) Design a procedure ismonotone(L) which checks if a list L with numerical entries is [strictly] monotonously decreasing or increasing. Return
 - -2 if the list is strictly monotonously decreasing,
 - -1 if the list is monotonously decreasing but not strictly,
 - +1 if the list is monotonously increasing but not strictly,
 - +2 if the list is strictly monotonously increasing,
 - but: 0 if all entries in the list are identical (which would be compatible with -1 as well as +1),
 - NULL otherwise.

 $^{^{1}}$ Remark: Some advanced numerical integration methods are implemented in Maple/int; they are activated if int is called with the option numeric.