

## Übungen zur Vorlesung Computermathematik

### Serie 3

**Aufgabe 3.1.** A matrix  $A \in \mathbb{R}^{n \times n}$  is strictly diagonally dominant if

$$\sum_{\substack{k=1 \\ k \neq j}}^n |A_{jk}| < |A_{jj}| \quad \text{für alle } j \in \{1, \dots, n\}.$$

Further, if a matrix is symmetric, strictly diagonally dominant and there holds  $A_{jj} > 0$  for all  $j \in \{1, \dots, n\}$ , then  $A$  is positive definite. Write a function `constructSPDmatrix` which returns for a give dimension  $n$  a random symmetric and positive definite (SPD) matrix  $A \in \mathbb{R}^{n \times n}$ . **Hint:** Use `rand()`. Note that  $A * A^T$  is symmetric for all  $A \in \mathbb{R}^{n \times n}$ . Use this to construct SPD-matrices.

**Aufgabe 3.2.** Let  $b \in \mathbb{R}^n$  and  $A \in \mathbb{R}^{n \times n}$  be a symmetric and positive definite (SPD) matrix. In order to solve the linear system  $Ax = b$ , one can use the CG-method. Write a MATLAB function `cgsolve`, which gets  $A$ ,  $b$  as well as a tolerance  $\tau > 0$  and returns the solution  $x$  of the linear system. The algorithm is obtained as follows: For an arbitrary initial guess  $x^{(0)} \in \mathbb{R}^n$  compute  $r^{(0)} := b - Ax^{(0)}$  and  $d^{(0)} := r^{(0)}$ . For all  $k \in \mathbb{N}$ , we define the sequences

$$\alpha^{(k)} := \frac{r^{(k)} \cdot r^{(k)}}{d^{(k)} \cdot Ad^{(k)}}, \quad x^{(k+1)} := x^{(k)} + \alpha^{(k)}d^{(k)}, \quad r^{(k+1)} := r^{(k)} - \alpha^{(k)}Ad^{(k)}$$

as well as

$$d^{(k+1)} := r^{(k+1)} + \frac{r^{(k+1)} \cdot r^{(k+1)}}{r^{(k)} \cdot r^{(k)}}d^{(k)}.$$

If the accuracy  $|r^{(k+1)}| \leq \tau$  is achieved, the CG-iteration should stop and return the current approximation  $x^{(k+1)} \approx x$ . Test your code with suitable examples. How does the number of CG-steps behave for  $\tau \rightarrow 0$  and big dimensions  $n \in \mathbb{N}$ . **Hinweis:** Use exercise 3.1.

**Aufgabe 3.3.** Aitken's  $\Delta^2$ -method is a method for convergence acceleration of sequences. For an injective sequence  $(x_n)$  with  $x = \lim_{n \rightarrow \infty} x_n$  one defines

$$y_n := x_n - \frac{(x_{n+1} - x_n)^2}{x_{n+2} - 2x_{n+1} + x_n} \tag{1}$$

Under certain assumptions for the sequence  $(x_n)$  it then holds

$$\lim_{n \rightarrow \infty} \frac{x - y_n}{x - x_n} = 0,$$

i.e., the sequence  $(y_n)$  converges faster to  $x$  than  $(x_n)$ . Write a MATLAB function `aitken` which takes a vector  $x \in \mathbb{R}^N$  and returns a vector  $y \in \mathbb{R}^{N-2}$ . Use suitable loops. Further, write an alternative MATLAB function `aitken_vec` which calculates the vector  $y \in \mathbb{R}^{N-2}$  with suitable vector arithmetic instead of loops. Think about how you can test your code! What happens for a geometric sequence  $x_n := q^n$  with  $0 < q < 1$ ?

**Aufgabe 3.4.** Write a MATLAB function `diffaitken`, which computes the approximation of the derivative of a function  $f$  in a point  $x$  through the forward and central difference quotient

$$\Phi(h) = \frac{f(x+h) - f(x)}{h} \quad \text{resp.} \quad \Phi(h) = \frac{f(x+h) - f(x-h)}{2h}.$$

Given the function  $f$ , the point  $x$  and an initial parameter  $h_0 > 0$ , the function returns an approximation of the derivative obtained as follows: For  $n \geq 1$ , compute  $h_n := 2^{-(n-1)}h_0$ ,  $x_n := \Phi(h_n)$ . Further, compute the sequence of the Aitken-extrapolation which is given by  $\phi_n := x_n$  für  $n = 1, 2$ , and  $\phi_n := y_{n-2}$  for  $n \geq 3$ . In this case  $y_n$  denote the sequence from exercise 3.3.

Additionally, compute the experimental rate of convergence for the forward and central difference quotient with and without Aitken-extrapolation. Visualize your results. What rates do you get?

**Aufgabe 3.5.** Consider the real nodes  $x_1 < \dots < x_n$  and function values  $y_j \in \mathbb{R}$ . Then, linear algebra provides a unique polynomial  $p(t) = \sum_{j=1}^n a_j t^{j-1}$  of degree  $n-1$ , such that  $p(x_j) = y_j$  for all  $j = 1, \dots, n$ . Suppose a fixed evaluation point  $t \in \mathbb{R}$ . The *Neville-algorithm* is able to compute the point evaluation  $p(t)$  without computing the vector of coefficients  $a \in \mathbb{R}^n$ . It consists of the following steps: First, define for  $j, m \in \mathbb{N}$  with  $m \geq 2$  and  $j + m \leq n + 1$  the values

$$p_{j,1} := y_j,$$

$$p_{j,m} := \frac{(t - x_j)p_{j+1,m-1} - (t - x_{j+m-1})p_{j,m-1}}{x_{j+m-1} - x_j}.$$

This implies  $p(t) = p_{1,n}$ . Write a MATLAB-function `neville` which computes  $p(t)$  for a given evaluation point  $t \in \mathbb{R}$  and vectors  $x, y \in \mathbb{R}^n$ . To do that, you can use the following scheme

$$\begin{array}{ccccccccccc}
 y_1 & = & p_{1,1} & \longrightarrow & p_{1,2} & \longrightarrow & p_{1,3} & \longrightarrow & \dots & \longrightarrow & p_{1,n} & = & p(t) \\
 & & & \nearrow & & \nearrow & & & & \nearrow & & & \\
 y_2 & = & p_{2,1} & \longrightarrow & p_{2,2} & & & & & \nearrow & & & \\
 & & & \nearrow & & & & & & & & & \\
 y_3 & = & p_{3,1} & \longrightarrow & \vdots & & & & & & & & (2) \\
 \vdots & & \vdots & & \vdots & \nearrow & & & & & & & \\
 y_{n-1} & = & p_{n-1,1} & \longrightarrow & p_{n-1,2} & & & & & & & & \\
 & & & \nearrow & & & & & & & & & \\
 y_n & = & p_{n,1} & & & & & & & & & & 
 \end{array}$$

One easy way to implement this scheme is by building a matrix with entries  $(p_{j,m})_{j,m=1}^n$ . For testing, take an arbitrary polynomial resp. nodes, and compute  $y_j = p(x_j)$ .

**Aufgabe 3.6.** One can implement the *Neville-algorithm* from exercise 3.5 without using additional memory. Therefore, instead of storing the values  $(p_{j,m})_{j,m=1}^n$  in a matrix, you can overwrite suitable entries in the given vector  $y$ . Write a MATLAB-function `neville2` which realizes the *Neville-algorithm* without using additional memory.

**Aufgabe 3.7.** One efficient way to compute the forward difference quotient  $\Phi(h)$  from exercise 3.4 is the *Richardson-extrapolation of the forward difference quotient*. The (theoretical!) idea is the following: Use the values  $\Phi(h_0), \dots, \Phi(h_n)$  to compute an interpolation polynomial of degree  $n-1$  with  $(h_j, \Phi(h_j))$  für  $j = 1, \dots, n$ . Then, there holds  $p_n(h) \approx \Phi(h)$  and one can use the *Neville-algorithm* to compute the point evaluation at  $h = 0$ . (A proof of convergence for this scheme is given in the lecture Numerischen Mathematik.) Write a function `richardson` which computes an approximation of  $f'(x)$  for a given function-handle  $f$ , evaluation point  $x \in \mathbb{R}$ , step-size  $h_0$  and tolerance  $\tau > 0$ . First, define  $h_n := 2^{-n}h_0$  and  $y_n := p_n(0)$ . Then, the function should return the first  $y_{n+1} \approx f'(x)$  which satisfies

$$|y_n - y_{n+1}| \leq \begin{cases} \tau, & \text{falls } |y_{n+1}| \leq \tau, \\ \tau |y_{n+1}| & \text{else.} \end{cases}$$

Use the function `neville` from exercise 3.5.

**Aufgabe 3.8.** One possible algorithm for eigenvalue computations is the *Power Iteration*. It approximates (under certain assumptions) the eigenvalue  $\lambda \in \mathbb{R}$  with the greatest absolute value of a symmetric matrix  $A \in \mathbb{R}^{n \times n}$  as well as the corresponding eigenvector  $x \in \mathbb{R}^n$ . The algorithm is obtained as follows: Given a vector  $x^{(0)} \in \mathbb{R}^n \setminus \{0\}$ , e.g.,  $x^{(0)} = (1, \dots, 1) \in \mathbb{R}^n$ , define the sequences

$$x^{(k)} := \frac{Ax^{(k-1)}}{\|Ax^{(k-1)}\|_2} \quad \text{and} \quad \lambda_k := x^{(k)} \cdot Ax^{(k)} := \sum_{j=1}^n x_j^{(k)} (Ax^{(k)})_j \quad \text{für } k \in \mathbb{N},$$

where  $\|y\|_2 := (\sum_{j=1}^n y_j^2)^{1/2}$  denotes the Euclidean norm. Then, under certain assumptions,  $(\lambda_k)$  converges towards  $\lambda$ , and  $(x^{(k)})$  converges towards an eigenvector associated to  $\lambda$  (in an appropriate sense). Write a MATLAB function `poweriteration`, which, given a matrix  $A$ , a tolerance  $\tau$  and an initial vector  $x^{(0)}$ , verifies whether the matrix  $A$  is symmetric. If this is not the case, then the function displays an error message and terminates (use `error`). Otherwise, it computes  $(\lambda_k)$  and  $(x^{(k)})$  until

$$\|Ax^{(k)} - \lambda_k x^{(k)}\|_2 \leq \tau \quad \text{and} \quad |\lambda_{k-1} - \lambda_k| \leq \begin{cases} \tau & \text{if } |\lambda_k| \leq \tau, \\ \tau|\lambda_k| & \text{else,} \end{cases}$$

and returns  $\lambda_k$  and  $x^{(k)}$ . Realize the function in an efficient way, i.e., avoid unnecessary computations (especially of matrix-vector products) and storage of data. Then, compare `poweriteration` with the built-in MATLAB function `eig`. Use the function `norm`, as well as MATLAB arithmetic.