Differential geometry (104.358) Exercise sheet for 03.5.2018

23. Calculate the induced metric of the catenoid

$$X: (u, v) \mapsto X(u, v) := O + e_1 \cosh(u) \cos(v) + e_2 \cosh(u) \sin(v) + e_3 u.$$

- 24. Show that a surface $X: \mathbb{R}^2 \supseteq U \to \mathcal{E}^3$ is conformally parametrised if and only if the parametrisation preserves angles.
- 25. Consider the sphere $S^2 \subset \mathbb{R}^3$ with radius 1 and centred at the origin. Let $N = (0,0,1) \in S^2$ be the north pole of the sphere. For every point (u,v,0) in the e_1e_2 -plane draw a line through (u,v,0) and N. This line cuts the sphere in the north pole and another point $\Pi(u,v)$ and thus defines a map

$$\Pi: \mathbb{R}^2 \to S^2 \subset \mathbb{R}^3,$$

 $(u, v) \mapsto \Pi(u, v).$

Calculate the map Π . What is the image of Π ? What is $\lim_{u\to\infty} \Pi(u,v)$?

After a choice of origin $O \in \mathcal{E}^3$, define Π a map X to \mathcal{E}^3 ,

$$X: \mathbb{R}^2 \to \mathcal{E}^3,$$

 $(u, v) \mapsto O + \Pi(u, v).$

Convince yourself that X is a regular parametrisation of the sphere without the north pole. Is the parametrisation conformal?

What is the image of a line in \mathbb{R}^2 under X? What is the image of a circle in \mathbb{R}^2 with centre at the origin under X?

Note: the inverse function Π^{-1} is called stereographic projection.

26. Let r > 0 and define a parametrisation of the Möbius strip by

$$X: \mathbb{R}^2 \to \mathcal{E}^3,$$

$$(u, v) \mapsto O + (e_1 \cos 2u + e_2 \sin 2u)(r + v \cos u) + e_3 v \sin u.$$

Calculate the Gauss map N of X.

Prove that
$$X(u+\pi) = X(u,0)$$
 but $N(u+\pi) = -N(u,0)$.

27. Let

$$X: \mathbb{R}^2 \supseteq U \to \mathcal{E}^3,$$

 $(u,v) \mapsto O + e_1 u + e_2 v + e_3 z(u,v),$

where $z: U \to \mathbb{R}$ is smooth.

Calculate the Gauss map and the shape operator of X.

Now let (u_0, v_0) be a stationary point of the function z. What does the shape operator and the Gauss curvature look like at this point?