

1. Tutorium - Lösungen

11.10.2013

1.1 Multiple Choice Fragen

$$a) \left[\begin{pmatrix} 0 & 1 \\ 2 & 3 \end{pmatrix} \right]^2 = \begin{pmatrix} 0 & 1 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 2 & 3 \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 6 & 11 \end{pmatrix}.$$

$$b) \sum_{i=1}^3 x_i^2 = (x_1)^2 + (x_2)^2 + (x_3)^2 = 1^2 + (-1)^2 + 2^2 = 6.$$

$$c) a_{10} + 2a_{11} + 3a_{22} = 0 + 2 \times 1 + 3 \times 1 = 5.$$

$$d) \sum_{m=1}^3 \sum_{n=1}^3 (a_{mn})^2 = \sum_{m=1}^3 [(a_{m1})^2 + (a_{m2})^2 + (a_{m3})^2] = a_{11}^2 + a_{12}^2 + a_{13}^2 + a_{21}^2 + a_{22}^2 + a_{23}^2 + a_{31}^2 + a_{32}^2 + a_{33}^2 \\ = 0^2 + (-1)^2 + (-1)^2 + 1^2 + 0^2 + (-1)^2 + 1^2 + 1^2 + 0^2 = 6.$$

$$e) \sum_{i=1}^3 a_i b_i = a_1 b_1 + a_2 b_2 + a_3 b_3 = 2 \times 1 + 4 \times 0 + 6 \times (-1) = -4.$$

$$f) e^{2ix} = 1 + 2ix + \frac{1}{2}(2ix)^2 + \frac{1}{3!}(2ix)^3 + \dots \text{ Gesuchter Term: } \frac{8}{6}i^3x^3 = -\frac{4}{3}ix^3.$$

$$g) \text{ Allgemeine Taylor-Reihe: } f(x) = \sum_{k=0}^{\infty} \frac{(x-x_0)^k}{k!} f^{(k)}(x_0).$$

$$f'(x) = -\sin(\sin(x)) \cos(x), \quad f''(x) = -\cos(\sin(x)) \cos^2(x) + \sin(\sin(x)) \sin(x),$$

$$f'''(x) = \sin(\sin(x)) \cos^3(x) + \cos(\sin(x)) 2 \cos(x) \sin(x) + \cos(\sin(x)) \cos(x) \sin(x) + \sin(\sin(x)) \cos(x).$$

$$f'''(0) = 0 \rightarrow \text{Term der dritten Ordnung verschwindet.}$$

Alternativ:

$$\cos(\sin x) = 1 - \frac{1}{2} \sin^2 x + \frac{1}{4!} \sin^4 x + \dots = 1 - \frac{1}{2} \left(x - \frac{1}{3!} x^3 + \dots \right)^2 + \dots = 1 - \frac{1}{2} x^2 + O(x^4) \text{ Nach dem Ausquadrieren kommen nur gerade Potenzen von } x \text{ vor} \rightarrow \text{es gibt keinen Term von der Ordnung } O(x^3).$$

$$h) \text{ Partiiell integrieren: } \int_0^1 x e^{2x} dx = x \frac{1}{2} e^{2x} \Big|_0^1 - \int_0^1 \frac{1}{2} e^{2x} dx = \frac{e^2}{2} - 0 - \frac{1}{4} e^{2x} \Big|_0^1 = \frac{e^2}{2} - \frac{e^2}{4} + \frac{1}{4} = \frac{e^2}{4} + \frac{1}{4}.$$

$$\text{Alternativ: } \int_0^1 x e^{2x} dx = \frac{d}{d\alpha} \int_0^1 e^{\alpha x} dx \Big|_{\alpha=2} = \frac{d}{d\alpha} \frac{e^{\alpha x}}{\alpha} \Big|_{x=0}^1 \Big|_{\alpha=2} = \frac{d}{d\alpha} \frac{e^{\alpha} - 1}{\alpha} \Big|_{\alpha=2} = \frac{e^{\alpha} \alpha - (e^{\alpha} - 1)}{\alpha^2} \Big|_{\alpha=2} = \frac{2e^2 - e^2 + 1}{4} \\ = \frac{e^2}{4} + \frac{1}{4}.$$

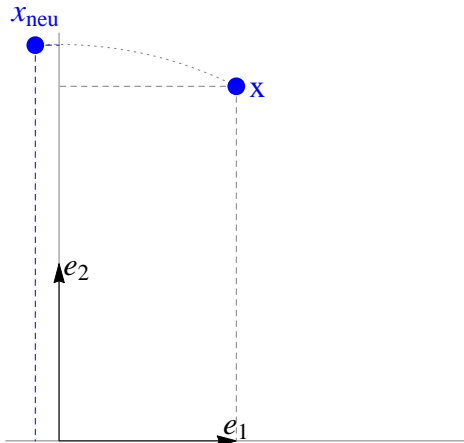
$$i) \frac{d}{dx} \tan(x^2) = \frac{d}{dx} \frac{\sin(x^2)}{\cos(x^2)} = \frac{\cos(x^2) \frac{d}{dx} \sin(x^2) - \sin(x^2) \frac{d}{dx} \cos(x^2)}{[\cos(x^2)]^2} = \frac{\cos(x^2) \cos(x^2) 2x + \sin(x^2) \sin(x^2) 2x}{[\cos(x^2)]^2} = \frac{2x}{[\cos(x^2)]^2}.$$

$$j) \frac{d}{d\alpha} \frac{d}{d\beta} [\cos(\alpha + \beta) \sin(\alpha - \beta)] = \frac{d}{d\alpha} [-\sin(\alpha + \beta) \sin(\alpha - \beta) - \cos(\alpha + \beta) \cos(\alpha - \beta)] \\ = -\cos(\alpha + \beta) \sin(\alpha - \beta) - \sin(\alpha + \beta) \cos(\alpha - \beta) + \sin(\alpha + \beta) \cos(\alpha - \beta) + \cos(\alpha + \beta) \sin(\alpha - \beta) = 0.$$

$$\text{Alternativ: erkenne, dass } -\sin(\alpha + \beta) \sin(\alpha - \beta) - \cos(\alpha + \beta) \cos(\alpha - \beta) = -\cos((\alpha + \beta) - (\alpha - \beta)) \\ = -\cos(2\beta), \text{ daher } \frac{d}{d\alpha} (-\cos(2\beta)) = 0.$$

1.2 Aktive und passive Drehung

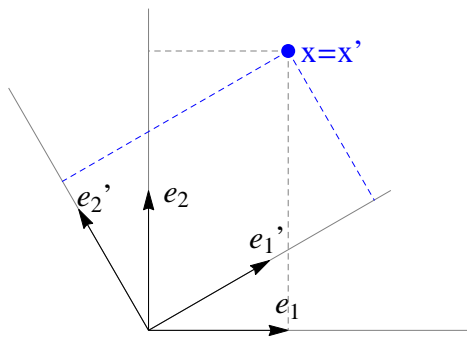
a)



$$b) R(\alpha) = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix}.$$

$$\mathbf{x}_{\text{neu}} = R(\alpha)\mathbf{x} = \begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} - 1 \\ \frac{1}{2} + \sqrt{3} \end{pmatrix} \approx \begin{pmatrix} -0.13 \\ 2.23 \end{pmatrix}.$$

c)



$$d) S(\alpha) = R(\alpha).$$

$$\mathbf{e}'_1 = S \mathbf{e}_1 = \begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} \\ \frac{1}{2} \end{pmatrix} \approx \begin{pmatrix} 0.87 \\ 0.5 \end{pmatrix}.$$

$$\mathbf{e}'_2 = S \mathbf{e}_2 = \begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \\ \frac{\sqrt{3}}{2} \end{pmatrix} \approx \begin{pmatrix} -0.5 \\ 0.87 \end{pmatrix}.$$

R und S sind ident.

$$e) T(\alpha) = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix}.$$

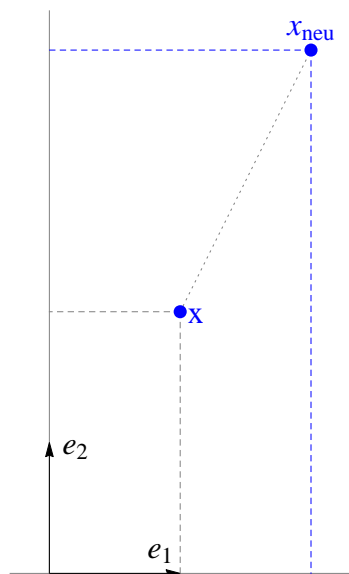
$$\mathbf{x}' = T \mathbf{x} = \begin{pmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 + \frac{\sqrt{3}}{2} \\ \sqrt{3} - \frac{1}{2} \end{pmatrix} \approx \begin{pmatrix} 1.87 \\ 1.23 \end{pmatrix}$$

R und T sind inverse zueinander. (Sie sind auch transponiert zueinander).

$$f) R(\alpha)T(\alpha) = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix} = \begin{pmatrix} \cos^2 \alpha + \sin^2 \alpha & \cos \alpha \sin \alpha - \sin \alpha \cos \alpha \\ \sin \alpha \cos \alpha - \cos \alpha \sin \alpha & \sin^2 \alpha + \cos^2 \alpha \end{pmatrix} \\ = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

1.3 Aktive und passive Skalierung

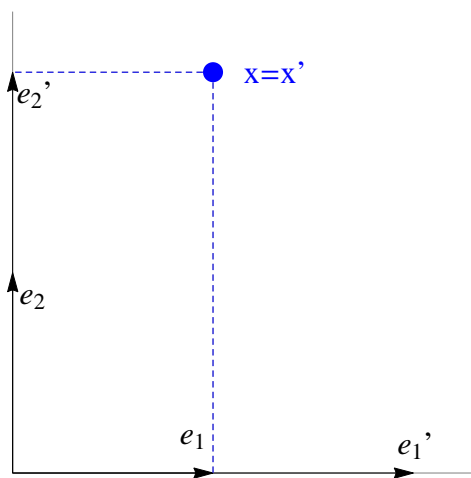
a)



b) $S(\lambda) = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$.

$$\mathbf{x}_{\text{neu}} = S(\lambda)\mathbf{x} = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \end{pmatrix}.$$

c)



d) $U(\lambda) = S(\lambda)$.

$$\mathbf{e}'_1 = U \mathbf{e}_1 = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}.$$

$$\mathbf{e}'_2 = U \mathbf{e}_2 = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \end{pmatrix}.$$

e) $V(\alpha) = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}$.

$$\mathbf{x}' = V \mathbf{x} = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix}$$

f) $S(\lambda)V(\lambda) = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 2 \times \frac{1}{2} & 0 \\ 0 & 2 \times \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$

$$g) \quad l = \sqrt{\mathbf{x}^T \mathbf{x}} = \sqrt{\begin{pmatrix} 1 & 2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix}} = \sqrt{1+4} = \sqrt{5}.$$

$$l' = \sqrt{\mathbf{x}'^T \mathbf{x}'} = \sqrt{\begin{pmatrix} \frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix}} = \sqrt{\frac{1}{4} + 1} = \frac{\sqrt{5}}{2}.$$

$$g(\lambda) = \begin{pmatrix} \lambda^2 & 0 \\ 0 & \lambda^2 \end{pmatrix}$$

$$\rightarrow \quad l = \sqrt{\mathbf{x}'^T g(\lambda) \mathbf{x}'} = \sqrt{\begin{pmatrix} \frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} \lambda^2 & 0 \\ 0 & \lambda^2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix}} = \sqrt{\begin{pmatrix} \frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 4 \end{pmatrix}} = \sqrt{5}.$$