

7. Tutorium - Lösungen

25.11.2016

- ANMERKUNG: Es liegt in der Verantwortung des Einzelnen, sich die Beispiele zunächst alleine und ganz ohne Hilfsmittel anzuschauen. Google, Wolfram Alpha, Lösungssammlungen, etc. helfen nur kurzfristig - leider nicht beim Test!

7.1 Residuensatz

a)  $\oint_C \frac{z}{z^2-z-2} dz = \oint_C \frac{z}{(z-2)(z+1)} dz = 2\pi i \left( \frac{z}{z+1} \Big|_{z=2} + \frac{z}{z-2} \Big|_{z=-1} \right) = 2\pi i \left( \frac{2}{3} + \frac{1}{3} \right) = 2\pi i$

b)  $\oint_C \frac{1}{2z^2-4z-16} dz = \oint_C \frac{1}{2(z-4)(z+2)} dz = 2\pi i \frac{1}{2(z-4)} \Big|_{z=-2} = 2\pi i \left( -\frac{1}{12} \right) = -\frac{1}{6}\pi i$

c)  $\oint_C \frac{z^3+z^2+1}{2(z+1)^3} dz = \oint_C \frac{1}{2(z+1)^3} \left[ 1 + (z+1) + \frac{1}{2}(-4(z+1)^2) + \frac{1}{3!}6(z+1)^3 \right] dz$   
 $= \oint_C \left[ \frac{1}{2(z+1)^3} + \frac{1}{2(z+1)^2} - \frac{1}{z+1} + \frac{1}{2} \right] = -2\pi i$

oder  $\oint_C \frac{z^3+z^2+1}{2(z+1)^3} dz = 2\pi i \frac{1}{2!} \frac{d^2}{dz^2} \frac{1}{2} (z^3+z^2+1) \Big|_{z=-1} = 2\pi i \frac{1}{2!} (3z+1) \Big|_{z=-1} = -2\pi i$

d)  $\oint_C \frac{e^{2z}}{z(z-1)} dz = 2\pi i \left( \frac{e^{2z}}{z-1} \Big|_{z=0} + \frac{e^{2z}}{z} \Big|_{z=1} \right) = 2\pi i(-1 + e^2)$

7.2 Gaußscher Integralsatz

a) Kugelfläche  $F : r = R$  (konstant)  $\rightarrow dx^1 = dr = 0 \rightarrow$  Basisvektoren :  $\mathbf{e}'_2 = \mathbf{e}'_\theta$  und  $\mathbf{e}'_3 = \mathbf{e}'_\phi$   
 Vektor in der Tangentialebene  
 $\mathbf{r}_T - \mathbf{r} = (\theta_T - \theta)\partial_\theta \mathbf{r} + (\phi_T - \phi)\partial_\phi \mathbf{r} = (\theta_T - \theta)\partial_\theta x^i \mathbf{e}_i + (\phi_T - \phi)\partial_\phi x^i \mathbf{e}_i = (\theta_T - \theta)\mathbf{e}_\theta + (\phi_T - \phi)\mathbf{e}_\phi$   
 Aus Bsp. 6.3:  
 $\mathbf{e}_\theta = \mathbf{e}'_2 = \partial_2 x^i \mathbf{e}_i = R \cos \theta \cos \phi \mathbf{e}_1 + R \cos \theta \sin \phi \mathbf{e}_2 - R \sin \theta \mathbf{e}_3$   
 $\mathbf{e}_\phi = \mathbf{e}'_3 = \partial_3 x^i \mathbf{e}_i = -R \sin \theta \sin \phi \mathbf{e}_1 + R \sin \theta \cos \phi \mathbf{e}_2$

Alternative Lösung:

$r = R \rightarrow x^2 + y^2 + z^2 = R^2 \rightarrow z = \pm \sqrt{R^2 - x^2 - y^2} \equiv f_\pm(x, y) \rightarrow \mathbf{r}(x, y) = x\mathbf{e}_x + y\mathbf{e}_y + f_\pm(x, y)\mathbf{e}_3$   
 Tangentialebene  $\mathbf{r} - \mathbf{r}_0 = (x_T - x)\partial_x \mathbf{r} + (y_T - y)\partial_y \mathbf{r}$   
 $\partial_x \mathbf{r}|_{r=R} = \mathbf{e}_1 + \partial_x f_\pm(x, y)\mathbf{e}_3 = \mathbf{e}_1 - (x/z)\mathbf{e}_3 = \mathbf{e}_1 - \tan \theta \cos \phi \mathbf{e}_3 = (R \cos \theta)^{-1} \cos \phi \mathbf{e}_\theta - (R \sin \theta)^{-1} \sin \phi \mathbf{e}_\phi$   
 $\partial_y \mathbf{r}|_{r=R} = \mathbf{e}_2 + \partial_y f_\pm(x, y)\mathbf{e}_3 = \mathbf{e}_2 - (y/z)\mathbf{e}_3 = \mathbf{e}_2 - \tan \theta \sin \phi \mathbf{e}_3 = (R \cos \theta)^{-1} \sin \phi \mathbf{e}_\theta + (R \sin \theta)^{-1} \cos \phi \mathbf{e}_\phi$   
 2 unabhängige Linearkombinationen von  $\mathbf{e}_\theta$  und  $\mathbf{e}_\phi$  können die Basisvektoren der Tangentialebene sein.

b)  $dF = |(dx'^2 \mathbf{e}'_2) \times (dx'^3 \mathbf{e}'_3)| = dx'^2 dx'^3 |\mathbf{e}'_2 \times \mathbf{e}'_3|$   
 $= dx'^2 dx'^3 |R^2 \cos \theta \sin \theta \cos^2 \phi \mathbf{e}_3 + R^2 \cos \theta \sin \theta \sin^2 \phi \mathbf{e}_3 + R^2 \sin^2 \theta \sin \phi \mathbf{e}_2 + R^2 \sin^2 \theta \cos \phi \mathbf{e}_1|$   
 $= dx'^2 dx'^3 |R^2 \sin^2 \theta \cos \phi \mathbf{e}_1 + R^2 \sin^2 \theta \sin \phi \mathbf{e}_2 + R^2 \cos \theta \sin \theta \mathbf{e}_3| = dx'^2 dx'^3 R^2 \sin \theta$

Aus Bsp.6.3  $(g'_{ij}) = (\mathbf{e}'_i \cdot \mathbf{e}'_j) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & R^2 & 0 \\ 0 & 0 & R^2 \sin^2 \theta \end{pmatrix} \rightarrow \det(\tilde{\mathbf{g}}') = g'_{22}g'_{33} - g'_{23}g'_{32} = R^4 \sin^2 \theta$

$dF = \sqrt{\det(\tilde{\mathbf{g}}')} d\theta d\phi$

Alternative Lösung:

Transformationsmatrix  $\mathbf{T} = t^i_j$ , Basistransformation  $\mathbf{e}'_j = t^i_j \mathbf{e}_i$   
 $dF = dx'^2 dx'^3 |\mathbf{e}'_2 \times \mathbf{e}'_3| = dx'^2 dx'^3 |(t^i_2 \mathbf{e}_i) \times (t^j_3 \mathbf{e}_j)| = dx'^2 dx'^3 |t^i_2 t^j_3 \varepsilon_{ij}^k \mathbf{e}_k|$   
 $= dx'^2 dx'^3 \sqrt{(\varepsilon_{ij}^k t^i_2 t^j_3 \mathbf{e}_k) \cdot (\varepsilon_{lm}^n t^l_2 t^m_3 \mathbf{e}_n)} = dx'^2 dx'^3 \sqrt{\varepsilon_{ij}^k \varepsilon_{lm}^n t^i_2 t^j_3 t^l_2 t^m_3 \delta_{kn}}$   
 $= dx'^2 dx'^3 \sqrt{\varepsilon_{ij}^k \varepsilon_{lm}^n t^i_2 t^j_3 t^l_2 t^m_3} = dx'^2 dx'^3 \sqrt{(\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) t^i_2 t^j_3 t^l_2 t^m_3}$   
 $= dx'^2 dx'^3 \sqrt{t^i_2 t^j_3 t_{i2} t_{j3} - t^i_2 t^j_3 t_{j2} t_{i3}} = dx'^2 dx'^3 \sqrt{t^i_2 t_{i2} t^j_3 t_{j3} - t^i_2 t_{i3} t^j_3 t_{j2}}$

$g'_{ij} = \mathbf{e}'_i \cdot \mathbf{e}'_j = (t^k_i \mathbf{e}_k) \cdot (t^l_j \mathbf{e}_l) = t^k_i t^l_j \delta_{kl} = t^k_i t^k_j$  (für orthonormale Basis,  $g_{kl} = \delta_{kl}$  und  $t^k_j = t_{kj}$ )

[Anmerkung : In der Transformationmatrix  $t^k_j$  zwischen den 2 Basen ist  $k$  der Index der kartesischen Koordinaten und  $j$  der Index der Kugelkoordinaten (orthogonal aber nicht-normiert). Deswegen  $t^k_j = t_{kj}$  aber  $t_{kj} = t^k_l g'_{lj} \neq t^{kj}$ .]

$\det(\tilde{\mathbf{g}}') = g'_{22}g'_{33} - g'_{23}g'_{32} = t^k_2 t_{k2} t^l_3 t_{l3} - t^k_2 t_{k3} t^l_3 t_{l2} \rightarrow dF = \sqrt{\det(\tilde{\mathbf{g}}')} dx'_2 dx'_3 = \sqrt{\det(\tilde{\mathbf{g}}')} d\theta d\phi$

c) Normalenvektor:  $\mathbf{n} = \frac{\mathbf{e}'_2 \times \mathbf{e}'_3}{|\mathbf{e}'_2 \times \mathbf{e}'_3|}$

$\rightarrow d\mathbf{F} = \mathbf{n} dF = \frac{\mathbf{e}'_2 \times \mathbf{e}'_3}{|\mathbf{e}'_2 \times \mathbf{e}'_3|} |\mathbf{e}'_2 \times \mathbf{e}'_3| d\theta d\phi = \mathbf{e}'_2 \times \mathbf{e}'_3 d\theta d\phi$

$= (R^2 \sin^2 \theta \cos \phi \mathbf{e}_1 + R^2 \sin^2 \theta \sin \phi \mathbf{e}_2 + R^2 \cos \theta \sin \theta \mathbf{e}_3) d\theta d\phi$

$= R^2 \sin \theta (\sin \theta \cos \phi \mathbf{e}_1 + \sin \theta \sin \phi \mathbf{e}_2 + \cos \theta \mathbf{e}_3) d\theta d\phi = R^2 \sin \theta \mathbf{e}'_1$

$\mathbf{w} = 2R \sin \theta \cos \phi \mathbf{e}_1 + R \cos \theta \mathbf{e}_3$

$\int_F \mathbf{w} \cdot d\mathbf{F} = \int_0^\pi d\theta \int_0^{2\pi} d\phi (2R^3 \sin^3 \theta \cos^2 \phi + R^3 \cos^2 \theta \sin \theta) = \int_0^\pi d\theta (2\pi R^3 \sin^3 \theta + 2\pi R^3 \cos^2 \theta \sin \theta)$

$= 2\pi R^3 \int_0^\pi d\theta \sin \theta = 4\pi R^3$

d) Volumen des Parallelepipedes (siehe Bsp.3.3 und 4.1) :  $dV = dx^1 dx^2 dx^3 |\mathbf{e}'_1 \cdot (\mathbf{e}'_2 \times \mathbf{e}'_3)| = dx^1 dx^2 dx^3 |\det(\mathbf{E}')|$   
wobei  $\mathbf{E}' = (\mathbf{e}'_1 \quad \mathbf{e}'_2 \quad \mathbf{e}'_3)$

Metrischer Tensor :  $\mathbf{g}' = \mathbf{E}'^T \mathbf{E}' \rightarrow \det(\mathbf{g}') = \det(\mathbf{E}'^T \mathbf{E}') = \det(\mathbf{E}'^T) \det(\mathbf{E}') = \det(\mathbf{E}')^2$

$\rightarrow dV = dx^1 dx^2 dx^3 \sqrt{\det(\mathbf{g}')} = r^2 \sin \theta dr d\theta d\phi$

e)  $\nabla \cdot \mathbf{w} = \partial_x (2r \sin \theta \cos \phi) + \partial_z (r \cos \theta) = \partial_x (2x) + \partial_z (z) = 2 + 1 = 3$

$\int_V \nabla \cdot \mathbf{w} dV = \int_0^R \int_0^\pi \int_0^{2\pi} 3r^2 \sin \theta d\phi d\theta dr = 6\pi \int_0^R r^2 dr \int_0^\pi \sin \theta d\theta = 6\pi \frac{R^3}{3} 2 = 4\pi R^3$

Gaußscher Integralsatz :  $\int_V \nabla \cdot \mathbf{w} dV = \int_F \mathbf{w} \cdot d\mathbf{F}$

Alternative Lösung:

$\mathbf{w} = 2r \sin \theta \cos \phi \mathbf{e}_1 + r \cos \theta \mathbf{e}_3$

$\nabla \cdot \mathbf{w} = \mathbf{e}^i \cdot \partial_i \mathbf{w} = \mathbf{e}^1 \cdot (2 \sin \theta \cos \phi \mathbf{e}_1 + \cos \theta \mathbf{e}_3) + \mathbf{e}^2 \cdot (2r \cos \theta \cos \phi \mathbf{e}_1 - r \sin \theta \mathbf{e}_3) + \mathbf{e}^3 \cdot (-2r \sin \theta \sin \phi \mathbf{e}_1)$

$\mathbf{e}^i = g^{ij} \mathbf{e}'_j \rightarrow \mathbf{e}'_1 = \mathbf{e}_1 = \sin \theta \cos \phi \mathbf{e}_1 + \sin \theta \sin \phi \mathbf{e}_2 + \cos \theta \mathbf{e}_3$

$\mathbf{e}'_2 = \frac{1}{r^2} \mathbf{e}'_2 = \frac{1}{r} \cos \theta \cos \phi \mathbf{e}_1 + \frac{1}{r} \cos \theta \sin \phi \mathbf{e}_2 - \frac{1}{r} \sin \theta \mathbf{e}_3, \quad \mathbf{e}'_3 = \frac{1}{r^2 \sin^2 \theta} \mathbf{e}'_3 = -\sin \phi / (r \sin \theta) \mathbf{e}_1 + \cos \phi / (r \sin \theta) \mathbf{e}_2$

$\rightarrow \nabla \cdot \mathbf{w} = 2 \sin \theta^2 \cos^2 \phi + \cos^2 \theta + 2 \cos^2 \theta \cos^2 \phi + \sin^2 \theta + 2 \sin^2 \phi = 3$

$\int_V \nabla \cdot \mathbf{w} dV = \int_V 3dV = 4\pi R^3$

### 7.3 Cauchyscher Hauptwert

a)  $\int_{C_1} \frac{1}{z^3 - z^2 + z - 1} dz = \int_{C_1} \frac{1}{(z-1)(z+i)(z-i)} dz = \int_0^\pi \frac{1}{(Re^{i\theta}-1)(Re^{i\theta}+i)(Re^{i\theta}-i)} iRe^{i\theta} d\theta$

$\left| \int_0^\pi \frac{1}{(Re^{i\theta}-1)(Re^{i\theta}+i)(Re^{i\theta}-i)} iRe^{i\theta} d\theta \right| \leq \int_0^\pi \left| \frac{1}{(Re^{i\theta}-1)(Re^{i\theta}+i)(Re^{i\theta}-i)} iRe^{i\theta} \right| d\theta = \int_0^\pi \left| \frac{1}{Re^{i\theta}-1} \right| \left| \frac{1}{Re^{i\theta}+i} \right| \left| \frac{1}{Re^{i\theta}-i} \right| R d\theta$   
 $\leq \int_0^\pi \left| \frac{1}{R-1} \right| \left| \frac{1}{-iR+i} \right| \left| \frac{1}{iR-i} \right| R d\theta = \frac{R}{|R-1|^3} \int_0^\pi d\theta = 2\pi \frac{R}{|R-1|^3} \xrightarrow{R \rightarrow \infty} 0$

$\lim_{R \rightarrow \infty} \int_{C_1} \frac{1}{z^3 - z^2 + z - 1} dz = 0$

b)  $\lim_{r \rightarrow 0} \int_{C_2} \frac{1}{z^3 - z^2 + z - 1} dz = \lim_{r \rightarrow 0} \oint_{C_2} \frac{1}{(z-1)(z+i)(z-i)} dz = \lim_{r \rightarrow 0} \underbrace{\int_0^\pi \frac{1}{re^{i\theta}(re^{i\theta} + 1 + i)(re^{i\theta} + 1 - i)} i r e^{i\theta} d\theta}_{z=re^{i\theta}+1}$

$= \lim_{r \rightarrow 0} \int_0^\pi \frac{1}{(re^{i\theta}+1+i)(re^{i\theta}+1-i)} i d\theta = \int_0^\pi \frac{i}{(1+i)(1-i)} d\theta = i \frac{\pi}{2}$

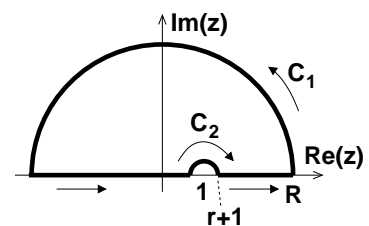
c)  $\mathcal{P} \int_{-\infty}^{\infty} \frac{1}{x^3 - x^2 + x - 1} dx$

$= \oint_C \frac{1}{z^3 - z^2 + z - 1} dz - \int_{C_1} \frac{1}{z^3 - z^2 + z - 1} dz + \int_{C_2} \frac{1}{z^3 - z^2 + z - 1} dz$

$= \oint_C \frac{1}{(z-1)(z+i)(z-i)} dz + i \frac{\pi}{2}$

$= 2\pi i \frac{1}{(z-1)(z+i)} \Big|_{z=i} + i \frac{\pi}{2} = \frac{\pi}{i-1} + i \frac{\pi}{2} = \frac{\pi(-i-1)}{2} + i \frac{\pi}{2} = -\frac{\pi}{2}$

Integrationspfad C



Anmerkung : Der Cauchysche Hauptwert ist unabhängig von Integrationspfad. Z.B.  $C'$  sei ein Integrationspfad wie  $C$  aber der obere Halbkreis  $C_2$  ist durch dem unteren Halbkreis  $C'_2 = \{z = re^{i\theta} | \pi \leq \theta \leq 2\pi\}$  ersetzt.

$\lim_{r \rightarrow 0} \int_{C'_2} \frac{1}{z^3 - z^2 + z - 1} dz = \int_\pi^{2\pi} \frac{i}{(1+i)(1-i)} d\theta = i \frac{\pi}{2}$

$\mathcal{P} \int_{-\infty}^{\infty} \frac{1}{x^3 - x^2 + x - 1} dx = \oint_{C'} \frac{1}{z^3 - z^2 + z - 1} dz - \int_{C_1} \frac{1}{z^3 - z^2 + z - 1} dz - \int_{C'_2} \frac{1}{z^3 - z^2 + z - 1} dz$

$= 2\pi i \frac{1}{(z-1)(z+i)} \Big|_{z=i} + 2\pi i \frac{1}{(z-i)(z+i)} \Big|_{z=1} - i \frac{\pi}{2} = \frac{\pi(-i-1)}{2} + i\pi - i \frac{\pi}{2} = -\frac{\pi}{2}$