

1. Test - Lösungen

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1 Rechenbeispiele [30 Punkte, 6 Punkte je Frage]

a) $\frac{1}{x_k x_k} \partial_i (x_i x_j x_j) = \frac{1}{x_k x_k} (\partial_i x_i) x_j x_j + 2 \frac{1}{x_k x_k} x_i x_j (\partial_i x_j) = \frac{x_j x_j}{x_k x_k} \delta_{ii} x_j x_j + 2 \frac{x_i x_j}{x_k x_k} \delta_{ij} = 3 \frac{x_j x_j}{x_k x_k} + 2 \frac{x_j x_j}{x_k x_k} = 5$

b) $\partial_i \sqrt{x_j x_j} = \frac{1}{2(x_k x_k)^{1/2}} \partial_i x_j x_j = \frac{1}{2|x|} 2 \delta_{ij} x_j = \frac{x_i}{|x|}$ (oder $\frac{x_i}{\sqrt{x_k x_k}}$)

c) $\mathbf{e}^1 \cdot \mathbf{e}_2 = 0 \rightarrow \mathbf{e}^1 = C_1(1 - 2), \quad \mathbf{e}^1 \cdot \mathbf{e}_1 = -C_1 = 1 \rightarrow C_1 = -1 \rightarrow \mathbf{e}^1 = (-1 \ 2)$

$\mathbf{e}^2 \cdot \mathbf{e}_1 = 0 \rightarrow \mathbf{e}^2 = C_2(1 - 1), \quad \mathbf{e}^2 \cdot \mathbf{e}_2 = C_2 = 1 \rightarrow \mathbf{e}^2 = (1 \ -1)$

alternative Lösung: $\begin{pmatrix} \mathbf{e}^1 \\ \mathbf{e}^2 \end{pmatrix} = (\mathbf{e}_1 \ \mathbf{e}_2)^{-1} = \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}$

d) $\varepsilon_{ijk} a^i a^j a^k = \det(a^i_j) = -4 + 1 = -3$

e) Da $\mathbf{g}^* = \mathbf{g}^{-1}$ und $g_{ij} = g_{ji}, g^{ij} g_{ij} = (\mathbf{g}^* \mathbf{g}^T)_{ii} = (\mathbf{g}^* \mathbf{g})_{ii} = \text{Tr}(\mathbf{1}) = d$

2 Tensoren [40 Punkte]

a) Eigenwertgleichung: $\begin{pmatrix} a^{11} & a^{12} \\ a^{21} & a^{22} \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \lambda \begin{pmatrix} u \\ v \end{pmatrix} \rightarrow \begin{pmatrix} a^{11} - \lambda & a^{12} \\ a^{21} & a^{22} - \lambda \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = 0$

$\rightarrow \det \begin{pmatrix} -\lambda & 1 \\ 1 & -\lambda \end{pmatrix} = \lambda^2 - 1 = 0 \rightarrow \lambda_1 = -1$ und $\lambda_2 = 1$

b) Eigenvektor: $\mathbf{e}'_i = s^j_i \mathbf{e}_j = (\mathbf{e}_1 \ \mathbf{e}_2) \begin{pmatrix} s^1_i \\ s^2_i \end{pmatrix}$

$\begin{pmatrix} a^{11} & a^{12} \\ a^{21} & a^{22} \end{pmatrix} \begin{pmatrix} s^1_i \\ s^2_i \end{pmatrix} = \begin{pmatrix} s^2_i \\ s^1_i \end{pmatrix} = \lambda \begin{pmatrix} s^1_i \\ s^2_i \end{pmatrix} \rightarrow s^2_i = \lambda s^1_i$ und $s^1_i = \lambda s^2_i$

Wenn $\lambda_1 = -1, \begin{pmatrix} s^1_1 \\ s^2_1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ (oder $\frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$). Wenn $\lambda_2 = 1, \begin{pmatrix} s^1_2 \\ s^2_2 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

Alternative :

a) und b)

Eigenwertgleichung $\begin{pmatrix} a^{11} & a^{12} \\ a^{21} & a^{22} \end{pmatrix} \begin{pmatrix} s^1_i \\ s^2_i \end{pmatrix} = \begin{pmatrix} s^2_i \\ s^1_i \end{pmatrix} = \lambda \begin{pmatrix} s^1_i \\ s^2_i \end{pmatrix} \rightarrow s^2_i = \lambda s^1_i$ und $s^1_i = \lambda s^2_i$

$\rightarrow s^1_i = \lambda^2 s^1_i \rightarrow \lambda^2 = 1 \rightarrow \lambda_1 = -1$ und $\lambda_2 = 1 \rightarrow \begin{pmatrix} s^1_1 \\ s^2_1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ und $\begin{pmatrix} s^1_2 \\ s^2_2 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

c) In der kartesischen Basis werden die Eigenvektoren \mathbf{e}'_i mit $\begin{pmatrix} s^1_i \\ s^2_i \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \mp 1 \end{pmatrix}$ dargestellt.

Deshalb sind die Projektoren in der kartesischen Basis gegeben, durch

$\begin{pmatrix} P^{11} & P^{12} \\ P^{21} & P^{22} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ -1 \end{pmatrix} (1 \ -1) = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$

$\begin{pmatrix} Q^{11} & Q^{12} \\ Q^{21} & Q^{22} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} (1 \ 1) = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$

d) Transformationsmatrix : $\mathbf{S} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$

Die kontravarianten Komponenten werden mit der Inverse $\mathbf{S}^{-1} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$ transformiert.

$\begin{pmatrix} P'^{11} & P'^{12} \\ P'^{21} & P'^{22} \end{pmatrix} = \mathbf{S}^{-1} \begin{pmatrix} P^{11} & P^{12} \\ P^{21} & P^{22} \end{pmatrix} (\mathbf{S}^{-1})^T = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$

$\begin{pmatrix} Q'^{11} & Q'^{12} \\ Q'^{21} & Q'^{22} \end{pmatrix} = \mathbf{S}^{-1} \begin{pmatrix} Q^{11} & Q^{12} \\ Q^{21} & Q^{22} \end{pmatrix} (\mathbf{S}^{-1})^T = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

Alternative :

c) und d)

In der Eigenbasis sind die Projektoren $\begin{pmatrix} P'^{11} & P'^{12} \\ P'^{21} & P'^{22} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ und $\begin{pmatrix} Q'^{11} & Q'^{12} \\ Q'^{21} & Q'^{22} \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

In der kartesischen Basis

$$\begin{pmatrix} P^{11} & P^{12} \\ P^{21} & P^{22} \end{pmatrix} = \mathbf{S} \begin{pmatrix} P'^{11} & P'^{12} \\ P'^{21} & P'^{22} \end{pmatrix} \mathbf{S}^T = \frac{1}{2} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} Q^{11} & Q^{12} \\ Q^{21} & Q^{22} \end{pmatrix} = \mathbf{S} \begin{pmatrix} Q'^{11} & Q'^{12} \\ Q'^{21} & Q'^{22} \end{pmatrix} \mathbf{S}^T = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

e)

$$\mathbf{A} = \lambda_1 \mathbf{E}_1 + \lambda_2 \mathbf{E}_2 \rightarrow \begin{pmatrix} a'^{11} & a'^{12} \\ a'^{21} & a'^{22} \end{pmatrix} = \lambda_1 \begin{pmatrix} P'^{11} & P'^{12} \\ P'^{21} & P'^{22} \end{pmatrix} + \lambda_2 \begin{pmatrix} Q'^{11} & Q'^{12} \\ Q'^{21} & Q'^{22} \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

Alternative:

$$\begin{pmatrix} a'^{11} & a'^{12} \\ a'^{21} & a'^{22} \end{pmatrix} = \mathbf{S}^{-1} \begin{pmatrix} a^{11} & a^{12} \\ a^{21} & a^{22} \end{pmatrix} (\mathbf{S}^{-1})^T = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$e) \begin{pmatrix} b'^{11} & b'^{12} \\ b'^{21} & b'^{22} \end{pmatrix} = e^{i\theta\lambda_1} \begin{pmatrix} P'^{11} & P'^{12} \\ P'^{21} & P'^{22} \end{pmatrix} + e^{i\theta\lambda_2} \begin{pmatrix} Q'^{11} & Q'^{12} \\ Q'^{21} & Q'^{22} \end{pmatrix} = \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & e^{i\theta} \end{pmatrix}$$

$$\begin{pmatrix} b^{11} & b^{12} \\ b^{21} & b^{22} \end{pmatrix} = \mathbf{S} \begin{pmatrix} b'^{11} & b'^{12} \\ b'^{21} & b'^{22} \end{pmatrix} \mathbf{S}^T = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & e^{i\theta} \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} \cos \theta & i \sin \theta \\ i \sin \theta & \cos \theta \end{pmatrix}$$

Alternative:

$$\begin{pmatrix} b^{11} & b^{12} \\ b^{21} & b^{22} \end{pmatrix} = e^{i\theta\lambda_1} \begin{pmatrix} P^{11} & P^{12} \\ P^{21} & P^{22} \end{pmatrix} + e^{i\theta\lambda_2} \begin{pmatrix} Q^{11} & Q^{12} \\ Q^{21} & Q^{22} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} e^{i\theta} + e^{-i\theta} & e^{i\theta} - e^{-i\theta} \\ e^{i\theta} - e^{-i\theta} & e^{i\theta} + e^{-i\theta} \end{pmatrix}$$

3 Lokale Transformation [30 Punkte]

a) Transformation der Basis: $\mathbf{dx} = dx^i \mathbf{e}_i = dx'^j (\partial'_j x^i) \mathbf{e}_i = dx'^j \mathbf{e}'_j \rightarrow \mathbf{e}'_j = \partial'_j x^i \mathbf{e}_i \quad (\partial'_j x^i = \frac{\partial x^i}{\partial x'^j})$

$$\mathbf{S} = (s^i_j) = (\partial'_j x^i) = \begin{pmatrix} v \cos \phi & u \cos \phi & -uv \sin \phi \\ v \sin \phi & u \sin \phi & uv \cos \phi \\ u & -v & 0 \end{pmatrix}$$

b)

$$\mathbf{g}' = \mathbf{S}^T \mathbf{S} \text{ (oder } g'_{ij} = \mathbf{e}'_i \cdot \mathbf{e}'_j) \rightarrow \mathbf{g}' = \begin{pmatrix} u^2 + v^2 & 0 & 0 \\ 0 & u^2 + v^2 & 0 \\ 0 & 0 & (uv)^2 \end{pmatrix}$$

$$\text{und } \mathbf{g}'^* = \mathbf{g}'^{-1} = \begin{pmatrix} 1/(u^2 + v^2) & 0 & 0 \\ 0 & 1/(u^2 + v^2) & 0 \\ 0 & 0 & 1/(uv)^2 \end{pmatrix}$$

Alternative Lösung für \mathbf{g}'^* :

$$\begin{pmatrix} \mathbf{e}'^1 \\ \mathbf{e}'^2 \\ \mathbf{e}'^3 \end{pmatrix} = \mathbf{S}^{-1} \begin{pmatrix} \mathbf{e}^1 \\ \mathbf{e}^2 \\ \mathbf{e}^3 \end{pmatrix}$$

$$(g'^{ij}) = (\mathbf{e}'^i \cdot \mathbf{e}'^j) = \mathbf{S}^{-1} \begin{pmatrix} \mathbf{e}^1 \\ \mathbf{e}^2 \\ \mathbf{e}^3 \end{pmatrix} \begin{pmatrix} \mathbf{e}^{1T} & \mathbf{e}^{2T} & \mathbf{e}^{3T} \end{pmatrix} (\mathbf{S}^{-1})^T = \mathbf{S}^{-1} (\mathbf{S}^{-1})^T = (\mathbf{S}^T \mathbf{S})^{-1} = \mathbf{g}'^{-1}$$

$$= \begin{pmatrix} 1/(u^2 + v^2) & 0 & 0 \\ 0 & 1/(u^2 + v^2) & 0 \\ 0 & 0 & 1/(uv)^2 \end{pmatrix}$$

$$c) \text{ In der dualen Basis } \mathbf{b}^T = -x^2 y \mathbf{e}^1 + x^3 \mathbf{e}^2 = \begin{pmatrix} -x^2 y & x^3 & 0 \end{pmatrix} \begin{pmatrix} \mathbf{e}^1 \\ \mathbf{e}^2 \\ \mathbf{e}^3 \end{pmatrix} = \begin{pmatrix} -x^2 y & x^3 & 0 \end{pmatrix} \mathbf{S} \begin{pmatrix} \mathbf{e}'^1 \\ \mathbf{e}'^2 \\ \mathbf{e}'^3 \end{pmatrix}$$

$$= \begin{pmatrix} -x^2 y v \cos \phi + x^3 v \sin \phi & -x^2 y u \cos \phi + x^3 u \sin \phi & x^2 y u v \sin \phi + x^3 u v \cos \phi \end{pmatrix} \begin{pmatrix} \mathbf{e}'^1 \\ \mathbf{e}'^2 \\ \mathbf{e}'^3 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 0 & u^4 v^4 \cos^2 \phi \end{pmatrix} \begin{pmatrix} \mathbf{e}'^1 \\ \mathbf{e}'^2 \\ \mathbf{e}'^3 \end{pmatrix}$$

$$\oint_C \mathbf{b} \cdot \mathbf{x} = \oint_C (u^4 v^4 \cos^2 \phi \mathbf{e}'^3) \cdot (dx'^i \mathbf{e}'_i) = \oint_C u^4 v^4 \cos^2 \phi \delta_i^3 dx'^i = \oint_{C_1} u^4 v^4 \cos^2 \phi dx'^3 = \int_0^{2\pi} \cos^2 \phi d\phi = \frac{1}{2} \int_0^{2\pi} (\cos(2\phi) + 1) d\phi = \pi$$