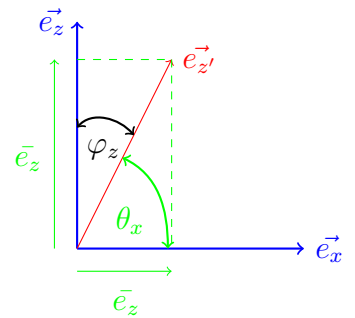
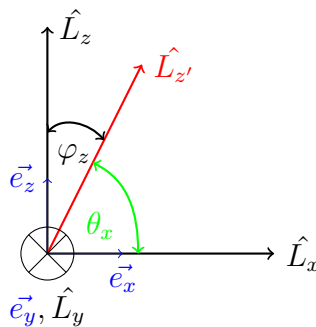
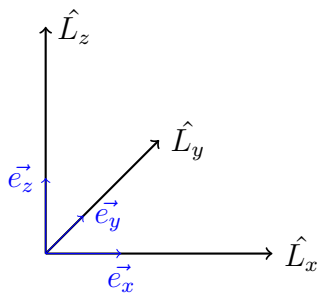


9. Tutorium - Quantentheorie I - 11.01.2013 - Lösung

1 allg. gilt:

$$\vec{L} = \vec{r} \times \vec{p} = \det \begin{pmatrix} \vec{e}_1 & x & \hat{p}_x \\ \vec{e}_2 & y & \hat{p}_y \\ \vec{e}_3 & z & \hat{p}_z \end{pmatrix} = \vec{e}_1 \cdot y \cdot \hat{p}_z + x \cdot \hat{p}_y \cdot \vec{e}_3 + \hat{p}_x \cdot \vec{e}_2 \cdot z - \vec{e}_3 \cdot y \cdot \hat{p}_x - z \cdot \hat{p}_y \cdot \vec{e}_1 - \hat{p}_z \cdot \vec{e}_2 \cdot x =$$

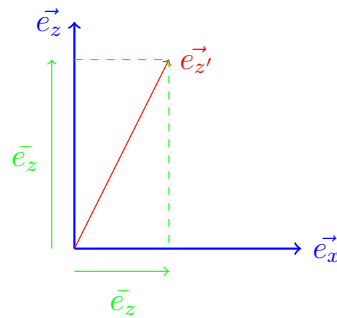
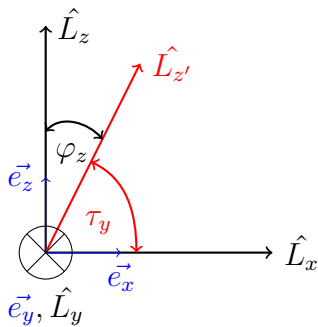
$$= \underbrace{(y \cdot \hat{p}_z - z \cdot \hat{p}_y)}_{\hat{L}_x} \cdot \vec{e}_1 + \underbrace{(\hat{p}_x \cdot z - \hat{p}_z \cdot x)}_{\hat{L}_y} \cdot \vec{e}_2 + \underbrace{(x \cdot \hat{p}_y - y \cdot \hat{p}_x)}_{\hat{L}_z} \cdot \vec{e}_3$$



blau ... kartesische Basisvektoren

gruen ... Basisvektoren bezogen auf die Achse z'

$$\cos(\theta_x) = \frac{\bar{e}_x}{e_x} \quad \cos(\varphi_z) = \frac{\bar{e}_z}{e_z} \quad \implies \vec{e}_{z'} = \bar{e}_x + \bar{e}_z = \cos(\theta_x) \cdot \vec{e}_x + \cos(\varphi_z) \cdot \vec{e}_z$$



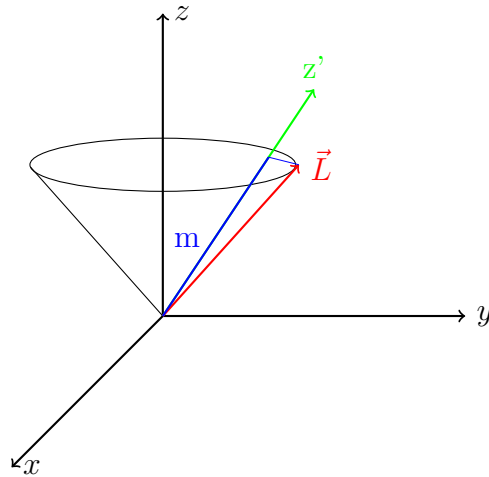
$$\cos(\tau_y) = \frac{\bar{e}_y}{e_y} \quad \implies \bar{e}_y = \cos(\tau_y) \cdot \vec{e}_y$$

Der neue Vektor als Funktion der alten kartesischen Basisvektoren:

$$\vec{e}_{z'} = \bar{e}_x + \bar{e}_y + \bar{e}_z = \cos(\theta_x) \cdot \vec{e}_x + \cos(\varphi_z) \cdot \vec{e}_z + \cos(\tau_y) \cdot \vec{e}_y$$

$$\begin{aligned}
\vec{e}_{z'} &= \begin{pmatrix} \cos(\theta_x) \cdot \vec{e}_x \\ \cos(\varphi_z) \cdot \vec{e}_z \\ \cos(\tau_y) \cdot \vec{e}_y \end{pmatrix} \implies \vec{L}_{z'} = \det \begin{pmatrix} \cos(\theta_x) \cdot \vec{e}_x & x & \hat{p}_x \\ \cos(\varphi_z) \cdot \vec{e}_z & y & \hat{p}_y \\ \cos(\tau_y) \cdot \vec{e}_y & z & \hat{p}_z \end{pmatrix} = \\
&= \cos(\theta_x) \cdot \vec{e}_x \cdot y \cdot \hat{p}_z + x \cdot \hat{p}_y \cdot \cos(\varphi_z) \cdot \vec{e}_z + \hat{p}_x \cdot \cos(\tau_y) \cdot \vec{e}_y \cdot z - \\
&\quad - \cos(\varphi_z) \cdot \vec{e}_z \cdot y \cdot \hat{p}_x - z \cdot \hat{p}_y \cdot \cos(\theta_x) \cdot \vec{e}_x - \hat{p}_z \cdot \cos(\tau_y) \cdot \vec{e}_y \cdot x = \\
&= \left(\cos(\theta_x) \cdot y \cdot \hat{p}_z - z \cdot \hat{p}_y \cdot \cos(\theta_x) \right) \cdot \vec{e}_x + \left(\hat{p}_x \cdot \cos(\tau_y) \cdot z - \hat{p}_z \cdot \cos(\tau) \cdot x \right) \cdot \vec{e}_y + \\
&\quad + \left(x \cdot \hat{p}_y \cdot \cos(\varphi_z) - \cos(\varphi_z) \cdot y \cdot \hat{p}_x \right) \cdot \vec{e}_z = \\
&= \left[\cos(\theta_x) \cdot \underbrace{\left(y \cdot \hat{p}_z - z \cdot \hat{p}_y \right)}_{\hat{L}_x} \right] \cdot \vec{e}_x + \left[\cos(\tau_y) \cdot \underbrace{\left(\hat{p}_x \cdot z - \hat{p}_z \cdot x \right)}_{\hat{L}_y} \right] \cdot \vec{e}_y + \left[\cos(\varphi_z) \cdot \underbrace{\left(x \cdot \hat{p}_y - y \cdot \hat{p}_x \right)}_{\hat{L}_z} \right] \cdot \vec{e}_z \\
&\implies \hat{L}_{z'} = \cos(\theta_x) \cdot \hat{L}_x \cdot \vec{e}_x + \cos(\tau_y) \cdot \hat{L}_y \cdot \vec{e}_y + \cos(\varphi_z) \cdot \hat{L}_z \cdot \vec{e}_z
\end{aligned}$$

$$\langle \psi | \hat{L}_{z'} | \psi \rangle = \cos(\theta_x) \cdot \langle \psi | \hat{L}_x | \psi \rangle + \cos(\tau_y) \cdot \langle \psi | \hat{L}_y | \psi \rangle + \cos(\varphi_z) \cdot \langle \psi | \hat{L}_z | \psi \rangle = \cos(\varphi_z) \cdot \hbar m$$



2 a) **angeregter Zustand:** $n = 2$

$$E_n = -\frac{\mu z^2 e^4}{8\varepsilon_0 h^2 n^2} \quad z = 1; \mu \dots \text{reduzierte Masse}$$

$$\Delta E_n = E_2 - E_1 = \frac{\mu e^4}{8\varepsilon_0 h^2} \left(\frac{1}{n_1^2} - \frac{1}{n_2^2} \right) = 1.634 \cdot 10^{-18} \text{ J}$$

$$\Delta E = hf = \hbar\omega$$

$$f = \frac{3\mu e^4}{32e_0^2 h^2} = 2.466 \cdot 10^{15} \text{ Hz}$$

$$c = \lambda f \longrightarrow \lambda = \frac{c}{f} = 1.215 \cdot 10^{-7} \text{ m} = 121.57 \text{ nm (UV)}$$

b) Eigenzustände $|nlm\rangle$ des Wasserstoffatoms \longrightarrow el. Dipolmoment ?
 \longrightarrow Erwartungswert $\langle nlm | \vec{d} | nlm \rangle$ des Dipoloperators $\vec{d} = -e\vec{r}$

$$\langle nlm | \vec{d} | nlm \rangle = \langle nlm | \underbrace{\pi\pi^{-1}}_{=1} | nlm \rangle = \langle nlm | (-1)^l \underbrace{\pi\vec{d}\pi^{-1}}_{-\vec{d}} | nlm \rangle =$$

$$= \langle nlm | \underbrace{(-1)^{2l}}_{=1 \dots l \in \mathbb{N}} (-1)\vec{d} | nlm \rangle = -(-1)^{2l} \langle nlm | \vec{d} | nlm \rangle = -\langle nlm | \vec{d} | nlm \rangle$$

$$\pi |nlm\rangle = (-1)^l |nlm\rangle$$

$$\longrightarrow \langle nlm | \vec{d} | nlm \rangle = -\langle nlm | \vec{d} | nlm \rangle = 0$$

3 a) Spin $s = \frac{1}{2} \rightarrow$ Zustand: $\chi = \frac{\sqrt{3}}{2} |+\rangle + \frac{i}{2} |-\rangle$

$|+\rangle, |-\rangle \dots$ EZ v. \hat{S}_z zu EW $\pm \frac{\hbar}{2}$

$$\hat{S}_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad EW : \begin{cases} -\frac{\hbar}{2} \rightarrow EV : \begin{pmatrix} 0 \\ 1 \end{pmatrix} = |-\rangle & \langle -| = (0 \ 1) \\ \frac{\hbar}{2} \rightarrow EV : \begin{pmatrix} 1 \\ 0 \end{pmatrix} = |+\rangle & \langle +| = (1 \ 0) \end{cases}$$

Wahrsch. bei Messung des Spins in z -Richtung $-\frac{\hbar}{2}$ zu erhalten?

$$|\langle \chi | - \rangle|^2 = \left| \left(\frac{\sqrt{3}}{2} \langle +| - \frac{i}{2} \langle -| \right) \cdot (|-\rangle) \right|^2 = \frac{1}{4}$$

b)

$$\hat{S}_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \frac{\hbar i}{2} (|-\rangle \langle +| - |+\rangle \langle -|)$$

$$\begin{aligned} \langle \hat{S}_y \rangle &= \langle \chi | \hat{S}_y | \chi \rangle = \left(\langle +| \frac{\sqrt{3}}{2} - \frac{i}{2} \langle -| \right) \cdot \left(\frac{\hbar i}{2} (|-\rangle \langle +| - |+\rangle \langle -|) \right) \cdot \left(\frac{\sqrt{3}}{2} |+\rangle + \frac{i}{2} |-\rangle \right) = \\ &= \dots = -\frac{i\hbar\sqrt{3}}{4} \cdot (i) \rightarrow \langle \hat{S}_y \rangle^2 = \frac{3\hbar^2}{16} \end{aligned}$$

$$\langle \hat{S}_y^2 \rangle = \langle \chi | \hat{S}_y^2 | \chi \rangle = \left(\frac{\sqrt{3}}{2} \langle +| - \frac{i}{2} \langle -| \right) \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cdot \left(\frac{\sqrt{3}}{2} |+\rangle + \frac{i}{2} |-\rangle \right) = \dots = \frac{\hbar^2}{4}$$

$$\Delta \hat{S}_y = \sqrt{\langle \hat{S}_y^2 \rangle - \langle \hat{S}_y \rangle^2} = \dots = \frac{\hbar}{4}$$

c) **Blochkugel:**

$$|\psi\rangle = \cos\left(\frac{\theta}{2}\right) |0\rangle + e^{i\varphi} \sin\left(\frac{\theta}{2}\right) |1\rangle$$

$$\frac{\hbar}{2} \rightarrow \text{messen} \rightarrow EV \begin{pmatrix} 1 \\ 0 \end{pmatrix} = |0\rangle$$

$$\varphi = \frac{\sqrt{3}}{2} |+\rangle + \frac{i}{2} |-\rangle$$

$$\cos\left(\frac{\theta}{2}\right) = \frac{\sqrt{3}}{2} \rightarrow \frac{\theta}{2} = \frac{\pi}{6} \rightarrow \theta = \frac{\pi}{3} = 60^\circ$$

$$e^{i\varphi} \cdot \sin\left(\frac{\theta}{2}\right) = \frac{i}{2} = i \cdot \frac{1}{2}$$

$$\sin\left(\frac{\theta}{2}\right) = \frac{1}{2} \rightarrow \frac{\theta}{2} = \frac{\pi}{6} \rightarrow \theta = 60^\circ$$

$$\cos(\varphi) + i\sin(\varphi) = e^{i\varphi} \stackrel{!}{=} i \rightarrow \varphi = \frac{1}{2}(4\pi n + \pi) \quad n \in \mathbb{Z}$$

$$\varphi = \frac{\pi}{2} = 90^\circ$$

4 a) **Eigenwerte:**

$$\hat{S}_y = \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \longrightarrow \text{EW: } \lambda = \pm 1 \quad E_1 = \pm \frac{\hbar}{2}$$

Eigenvektoren:

$$\lambda_1 = \frac{\hbar}{2}$$

$$\begin{pmatrix} -\frac{\hbar}{2} & -i\frac{\hbar}{2} \\ i\frac{\hbar}{2} & -\frac{\hbar}{2} \end{pmatrix} \vec{x} = \vec{0} \longrightarrow EV_1 = \begin{pmatrix} 1 \\ -i \end{pmatrix}$$

$$\lambda_2 = -\frac{\hbar}{2}$$

$$\frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \vec{x} = \vec{0} \longrightarrow EV_2 = \begin{pmatrix} 1 \\ i \end{pmatrix}$$

$$\hat{S}_y |\chi(0)\rangle = \frac{\hbar}{2} |\chi(0)\rangle$$

$$\hat{S}_y \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm i \end{pmatrix} = \frac{\hbar}{2} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm i \end{pmatrix}$$

b)

$$\hat{S}_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \longrightarrow \hat{S}_x |\pm\rangle_x = \pm \frac{\hbar}{2} |\pm\rangle_x \longrightarrow \text{EV v. } \hat{S}_x \text{ f\"ur } \pm \frac{\hbar}{2} : \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix}$$

$$|\pm\rangle_x = \frac{1}{\sqrt{2}} (|+\rangle \pm |-\rangle)$$

Zeitentwicklung von $|\chi(0)\rangle$

$$W\left(+\frac{\hbar}{2}\right) = |\langle +|_x \chi(t)\rangle|^2 \stackrel{!}{=} 1$$

$$\left| \frac{1}{\sqrt{2}} (\langle +| + \langle -|) \cdot (e^{-\frac{i\gamma B t}{2}} |+\rangle + i \cdot e^{\frac{i\gamma B t}{2}} |-\rangle) \right|^2 = \dots = \frac{1}{2} - \frac{1}{2} \sin(\gamma B t) \stackrel{!}{=} 1$$

$$\text{wobei } \sin(\varphi) = \frac{e^{i\varphi} - e^{-i\varphi}}{2} \text{ ben\"utzt wurde}$$

$$1 - \sin(\gamma B t) = 2 \longrightarrow \sin(\gamma B t) = -1$$

und somit erhalten wir:

$$B = \frac{3\pi}{2\gamma t}$$