Black Holes I — Exercise sheet 3

(3.1) Lorentz tensor gymnastics

Take the following Lorentz tensor and vector

$$T_{\mu\nu} = \begin{pmatrix} 2 & 0 & 0 & 0\\ 0 & -1 & 3 & 0\\ 0 & 3 & 2 & 0\\ 0 & 0 & 0 & 1 \end{pmatrix} \qquad k_{\mu} = \begin{pmatrix} -3\\ 1\\ 2\\ -2 \end{pmatrix}$$

and calculate the following quantities

- (a) $T^{\mu\nu}$ and $T^{\mu}{}_{\mu}$
- (b) k^{μ} and $k_{\mu}k^{\mu}$ (is k time-, light- or spacelike?)
- (c) $T_{(\mu\nu)} = \frac{1}{2} (T_{\mu\nu} + T_{\nu\mu})$ and $T_{[\mu\nu]} = \frac{1}{2} (T_{\mu\nu} T_{\nu\mu})$
- (d) $T_{\mu\nu}k^{\nu}$ and $T_{\mu\nu}k^{\mu}k^{\nu}$
- (e) $T_{\mu\nu}T^{\nu\lambda}$ [using the result for (a)]

(3.2) Euler–Lagrange equations

Vary the following actions and write down the Euler-Lagrange equations of motion:

(a)
$$S = -\int dt \left| q^i \dot{p}_i + H(q^i, p_i) \right|$$

- (a) $S = -\int dt \left[q^{i} \dot{p}_{i} + H(q^{i}, p_{i}) \right]$ (b) $S = \int dt \left[k_{1}(q) \ddot{q} + k_{2}(q) \dot{q} V(q) \right]$
- (c) $S = -\frac{1}{2} \int d^n x \left[(\partial_i \phi) (\partial_j \phi) \eta^{ij} m^2 \phi^2 + \lambda \phi^4 \right] \quad i, j = 0, 1, \dots, (n-1)$
- (d) $S = \int dt q$

(3.3) Minkowski metric in rotating coordinates

Start with the Minkowski line-element

$$ds^{2} = \eta_{\mu\nu} \, dx^{\mu} dx^{\nu} = -dt^{2} + dx^{2} + dy^{2} + dz^{2}$$

and introduce "rotating coordinates"

$$t' = t$$
 $x' = r \cos(\phi - \omega t)$ $y' = r \sin(\phi - \omega t)$ $z' = z$

where $r = \sqrt{x^2 + y^2}$ and $\phi = \arctan(y/x)$. Find the components of the metric $g_{\mu\nu}$ and its inverse $g^{\mu\nu}$ in these coordinates, where

$$ds^{2} = g_{\mu\nu} \, dx'^{\mu} dx'^{\nu} = \eta_{\mu\nu} \, dx^{\mu} dx^{\nu}$$

These exercises are due on November 19th 2013.

Hints:

- Remember the Einstein summation convention, i.e., to sum over contracted indices. Indices are raised with the inverse Minkowski metric $\eta^{\mu\nu} = \text{diag}(-1, 1, 1, 1)^{\mu\nu}$ and lowered with the Minkowski metric $\eta_{\mu\nu} = \text{diag}(-1, 1, 1, 1)_{\mu\nu}$.
- You may drop all boundary terms/total derivative terms and use partial integrations whenever a derivative acts on a variation (you may also keep boundary terms, and you will have made your first step towards understanding D-branes). And yes, the answer you get for the equations of motion in the case (d) is really strange...
- Remember that $dx'^{\mu} = dx^{\nu} \frac{\partial x'^{\mu}}{\partial x^{\nu}}$ and insert this into the last formula to extract $g_{\mu\nu}$. You get $g^{\mu\nu}$ e.g. from taking the matrix inverse of $g_{\mu\nu}$, but this is not the only possibility.