

## Computation exercise 2(b): Actuator design

Mechatronic systems  
376.050  
2014W

Important: Answers must be a hard copy and submitted to the office in CA0421 by December 17, 2014 at 4pm. The work must be original.

Fig. 1 shows a lumped mass model of a positioning system using a piezo actuator. The power is provided by a voltage amplifier. The disturbance to be corrected has a power spectral density of  $1 \text{ nm}/\sqrt{\text{Hz}}$  and a bandwidth of 7.5 kHz. The assignment is to compute amplifier requirements in terms of voltage and current.

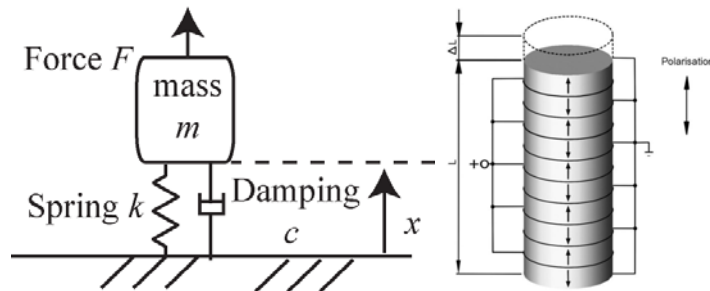


Fig. 1: A lumped mass model of a positioning system and the stacked piezo actuator

Parameter	Value	Unit	
$Y$	$53 \cdot 10^9$	$\text{N/m}^2$	Youngs modulus
$m$	10	g	Weight mass
$\rho$	$7.85 \cdot 10^3$	$\text{Kg/m}^3$	Density piezo
$c$	10	$\text{N}/(\text{m/s})$	Damping
$l_0$	25	mm	Length piezo
$r$	5	mm	Radius piezo
$d$	$195 \cdot 10^{-12}$	$\text{m/V}$	Piezoelectric coefficient
$\epsilon$	$1.68 \cdot 10^{-8}$	$\text{F/m}$	Dielectric coefficient
$n$	170	~	Number of stacks
$R$	50	$\Omega$	Output impedance

- Determine the mass, stiffness and the capacity of the piezo [15%]
- Determine the transfer function from input voltage to displacement and the impedance of the piezo amplifier [30%]
- Determine the required voltage and current [30%]